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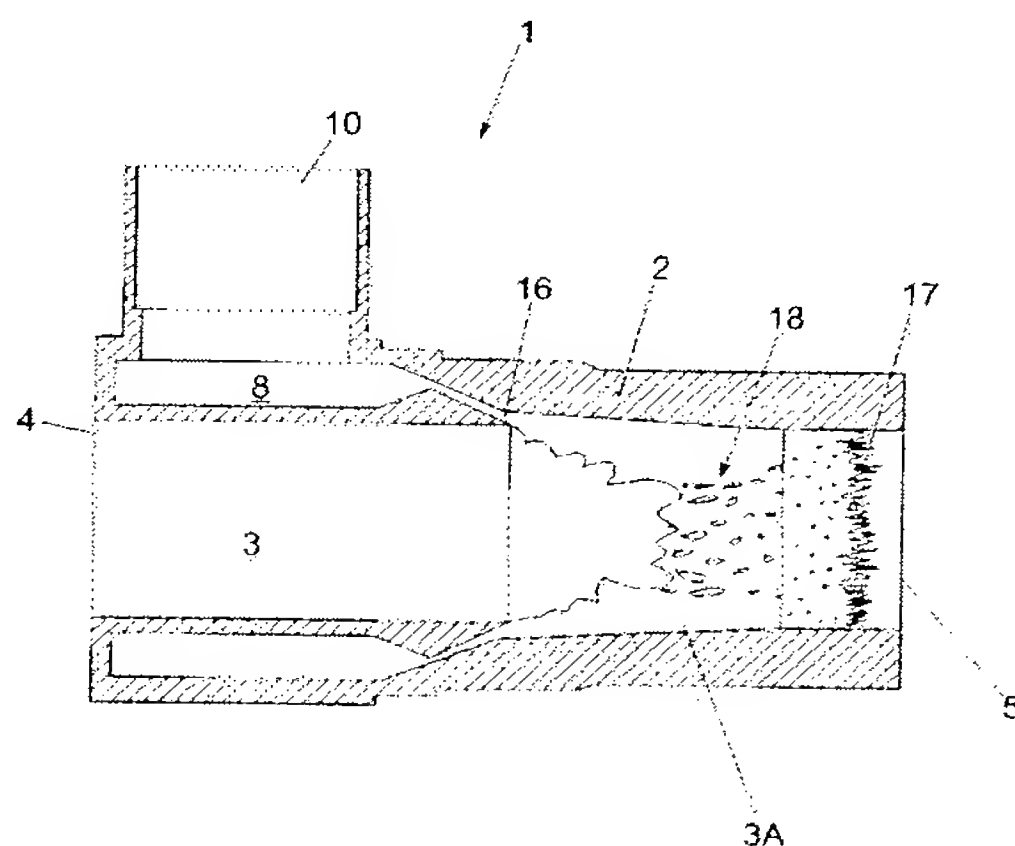
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(54) Title: JET PUMP



(57) Abstract: A fluid mover (1) includes a hollow body (2) provided with a straight-through passage (3) of substantially constant cross section with an inlet end (4) an outlet end (5) for the entry and discharge respectively of a working fluid. A nozzle (16) substantially circumscribes and opens into the passage (3) intermediate the inlet (4) and outlet (5) ends. An inlet (10) communicates with the nozzle (16) for the introduction of a transport fluid and a mixing chamber (3A) is formed within the passage (3) downstream of the nozzle (16). The nozzle internal geometry and the bore profile immediately upstream of the nozzle exit are disposed and configured to optimise the energy transfer between the transport fluid and working fluid. In use, through the introduction of transport fluid, the working fluid or fluids are atomised to form a dispersed vapour/droplet flow regime with locally supersonic flow conditions within a pseudo-vena contracta, resulting in the creation of a supersonic condensation shock wave (17) within the downstream mixing chamber (3A) by the condensation of the transport fluid. Methods of moving and processing fluids using the fluid mover are also disclosed.

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JET PUMP

1 This invention relates to a method and apparatus for
2 moving a fluid.

3
4 The present invention has reference to improvements
5 to a fluid mover having a number of practical
6 applications of diverse nature ranging from marine
7 propulsion systems to pumping applications for
8 moving and/or mixing fluids and/or solids of the
9 same or different characteristics. The present
10 invention also has relevance in the fields inter
11 alia of heating, cooking, cleaning, aeration, gas
12 fluidisation, and agitation of fluids and
13 fluids/solids mixtures, particle separation,
14 classification, disintegration, mixing,
15 emulsification, homogenisation, dispersion,
16 maceration, hydration, atomisation, droplet
17 production, viscosity reduction, dilution, shear
18 thinning, transport of thixotropic fluids and
19 pasteurisation.

1

2 More particularly the invention is concerned with
3 the provision of an improved fluid mover having
4 essentially no moving parts.

5

6 Ejectors are well known in the art for moving
7 working or process fluids by the use of either a
8 central or an annular jet which emits steam into a
9 duct in order to move the fluids through or out of
10 appropriate ducting or into or through another body
11 of fluid. The ejector principally operates on the
12 basis of inducing flow by creating negative
13 pressure, generally by the use of the venturi
14 principle. The majority of these systems utilise a
15 central steam nozzle where the induced fluid
16 generally enters the duct orthogonally to the axis
17 of the jet, although there are exceptions where the
18 reverse arrangement is provided. The steam jet is
19 accelerated through an expansion nozzle into a
20 mixing chamber where it impinges on and is mixed
21 with working fluid. The mixture of working fluid
22 and steam is accelerated to higher velocities within
23 a downstream convergent section prior to a divergent
24 section, e.g. a venturi. The pressure gradient
25 generated in the venturi induces new working fluid
26 to enter the mixing chamber. The energy transfer
27 mechanism in most steam ejector systems is a
28 combination of momentum, heat and mass transfer but
29 by varying proportions. Many of these systems
30 employ the momentum transfer associated with a
31 converging flow, while others involve the generation
32 of a shock wave in the divergent section. One of

1 the major limitations of the conventional
2 convergent/divergent systems is that their
3 performance is very sensitive to the position of the
4 shock wave which tends to be unstable, easily moving
5 away from its optimum position. It is known that if
6 the shock wave develops in the wrong place within
7 the convergent/divergent sections, the relevant unit
8 may well stall. Such systems can also only achieve
9 a shock wave across a restricted section.

10

11 Furthermore, for systems which employ a central
12 steam nozzle, the throat dimension restriction and
13 the sharp change of direction affecting the working
14 fluid presents a serious limitation on the size of
15 any particulate throughput and certainly any rogue
16 material that might enter the system could cause
17 blockage.

18

19 An improved fluid mover is described in our
20 International Patent Application No
21 PCT/GB2003/004400 in which the interaction of a
22 working fluid or fluids and a transport fluid
23 projected from a nozzle arrangement provides
24 pumping, entrainment, mixing, heating,
25 emulsification, and homogenization etc. of the
26 working fluid or fluids. The fluid mover introduces
27 an annular supersonic jet of transport fluid,
28 typically steam, into a relatively large diameter
29 straight through hollow passage. Through a
30 combination of momentum transfer, high shear, and
31 the generation of a condensation shock wave, the
32 high velocity steam induces and acts upon the

1 working fluid passing through the centre of the
2 hollow body.

3

4 PCT/GB2003/004400 describes that the transport fluid
5 is preferably a condensable fluid and may be a gas
6 or vapour, for example steam, which may be
7 introduced in either a continuous or discontinuous
8 manner. At or near the point of introduction of the
9 transport fluid, for example immediately downstream
10 thereof, a pseudo-vena contracta or pseudo
11 convergent/divergent section is generated, akin to
12 the convergent/divergent section of conventional
13 steam ejectors but without the physical constraints
14 associated therewith since the relevant section is
15 formed by the effect of the steam impacting upon the
16 working or process fluid. Accordingly the fluid
17 mover is more versatile than conventional ejectors
18 by virtue of a flexible fluidic internal boundary
19 described by the pseudo-vena contracta. The
20 flexible boundary lies between the working fluid at
21 the centre and the solid wall of the unit, and
22 allows disturbances or pressure fluctuations in the
23 multi phase flow to be accommodated better than for
24 a solid wall. This advantageously reduces the
25 supersonic velocity within the multi phase flow,
26 resulting in better droplet dispersion, increasing
27 the momentum transfer zone length, thus producing a
28 more intense condensation shock wave.

29

30 PCT/GB2003/004400 further discloses that the
31 positioning and intensity of the shock wave is
32 variable and controllable depending upon the

1 specific requirements of the system in which the
2 fluid mover is disposed. The mechanism relies on a
3 combination of effects in order to achieve its high
4 versatility and performance, notably heat, momentum
5 and mass transfer which gives rise to the generation
6 of the shock wave and also provides for shearing of
7 the working fluid flow on a continuous basis by
8 shear dispersion and/or dissociation. Preferably
9 the nozzle is located as close as possible to the
10 projected surface of the working fluid in practice
11 and in this respect a knife edge separation between
12 the transport fluid or steam and the working fluid
13 stream is of advantage in order to achieve the
14 requisite degree of interaction. The angular
15 orientation of the nozzle with respect to the
16 working fluid stream is of importance and may be
17 shallow.

18
19 Further, PCT/GB2003/004400 discloses that the or
20 each transport fluid nozzle may be of a convergent-
21 divergent geometry internally thereof, and in
22 practice the nozzle is configured to give the
23 supersonic flow of transport fluid within the
24 passage. For a given steam condition, i.e. dryness,
25 pressure and temperature, the nozzle is preferably
26 configured to provide the highest velocity steam
27 jet, the lowest total pressure drop and the highest
28 static enthalpy between the steam chamber and the
29 nozzle exit. The nozzle is preferably configured to
30 avoid any shock in the nozzle itself. For example
31 only, and not by way of limitation, an optimum area
32 ratio for the nozzle, namely exit area: throat area,

1 lies in the range 1.75 and 7.5, with an included
2 angle of less than 9°.

3

4 The or each nozzle is conveniently angled towards
5 the working fluid flow and also faces generally
6 towards the outlet of the fluid mover. This helps
7 penetration of the working fluid by the transport
8 fluid, which may help shear or thermal dispersion of
9 the working fluid. This may also prevent both
10 kinetic energy dissipation on the wall of the
11 passage and premature condensation of the steam at
12 the wall of the passage, where an adverse
13 temperature differential prevails. The angular
14 orientation of the nozzles is selected for optimum
15 performance which is dependent inter alia on the
16 nozzle orientation and the internal geometry of the
17 mixing chamber. Further the angular orientation of
18 the or each nozzle is selected to control the
19 pseudo-convergent/divergent profile, the pressure
20 profile within the mixing chamber, the enthalpy
21 addition and the condensation shock wave intensity
22 or position in accordance with the pressure and flow
23 rates required from the fluid mover. Moreover, the
24 creation of turbulence, governed inter alia by the
25 angular orientation of the nozzle, is important to
26 achieve optimum performance by dispersal of the
27 working fluid to a vapour-droplet phase in order to
28 increase acceleration by momentum transfer. This
29 aspect is of particular importance when the fluid
30 mover is employed as a pump. For example, and not
31 by way of limitation, in the present invention it
32 has been found that an angular orientation for the

1 or each nozzle may lie in the range 0 to 30° with
2 respect to the flow direction of the working fluid.

3
4 A series of nozzles with respective mixing chamber
5 sections associated therewith may be provided
6 longitudinally of the passage and in this instance
7 the nozzles may have different angular orientations,
8 for example decreasing from the first nozzle in a
9 downstream direction. Each nozzle may have a
10 different function from the other or others, for
11 example pumping, mixing, disintegrating, and may be
12 selectively brought into operation in practice.
13 Each nozzle may be configured to give the desired
14 effects upon the working fluid. Further, in a
15 multi-nozzle system by the introduction of the
16 transport fluid, for example steam, phased heating
17 may be achieved. This approach may be desirable to
18 provide a gradual heating of the working fluid.

19
20 An object of the present invention is to improve the
21 performance of the fluid mover by enhancing the
22 energy transfer mechanism between the high velocity
23 transport fluid and the working fluid. This
24 improves the performance of the fluid mover having
25 essentially no moving parts having an improved
26 performance than fluid movers currently available in
27 the absence of any constriction such as is
28 exemplified in the prior art recited in the
29 aforementioned patent.

30
31 According to a first aspect of the present invention
32 a fluid mover includes a hollow body provided with a

1 straight-through passage of substantially constant
2 cross section with an inlet at one end of the
3 passage and an outlet at the other end of the
4 passage for the entry and discharge respectively of
5 a working fluid, a nozzle substantially
6 circumscribing and opening into said passage
7 intermediate the inlet and outlet ends thereof, an
8 inlet communicating with the nozzle for the
9 introduction of a transport fluid, a mixing chamber
10 being formed within the passage downstream of the
11 nozzle, the nozzle internal geometry and the bore
12 profile immediately upstream of the nozzle exit
13 being so disposed and configured to optimise the
14 energy transfer between the transport fluid and
15 working fluid that in use through the introduction
16 of transport fluid the working fluid or fluids are
17 atomised to form a dispersed vapour/droplet flow
18 regime with locally supersonic flow conditions
19 within a pseudo-vena contracta, resulting in the
20 creation of a supersonic condensation shock wave
21 within the downstream mixing chamber by the
22 condensation of the transport fluid.

23

24 The transport fluid is preferably a condensable
25 fluid and may be a gas or vapour, for example steam,
26 which may be introduced in either a continuous or
27 discontinuous manner.

28

29 According to a second aspect of the present
30 invention a fluid mover of the kind described in our
31 aforementioned patent application, includes a hollow
32 body provided with a straight-through passage of

1 substantially constant cross section with an inlet
2 at one end of the passage and an outlet at the other
3 end of the passage for the entry and discharge
4 respectively of a working fluid, a nozzle
5 substantially circumscribing and opening into said
6 passage intermediate the inlet and outlet ends
7 thereof, an inlet communicating with the nozzle for
8 the introduction of steam, a mixing chamber being
9 formed within the passage downstream of the nozzle,
10 the nozzle internal geometry and the bore profile
11 immediately upstream of the nozzle exit being so
12 disposed and configured to optimise the energy
13 transfer between the steam and working fluid that in
14 use through the introduction of steam the working
15 fluid or fluids are atomised to form a dispersed
16 vapour/droplet flow regime with locally supersonic
17 flow conditions within a pseudo-vena contracta,
18 resulting in the creation of a supersonic
19 condensation shock wave within the downstream mixing
20 chamber by the condensation of the steam.

21
22 The nozzle may be of a form to correspond with the
23 shape of the passage and thus for example a circular
24 passage would advantageously be provided with an
25 annular nozzle circumscribing it. The term
26 'annular' as used herein is deemed to embrace any
27 configuration of nozzle or nozzles that
28 circumscribes the passage of the fluid mover, and
29 encompasses circular, irregular, polygonal and
30 rectilinear shapes of nozzle. The term
31 "circumscribing" or "circumscribes" as used herein
32 is deemed to embrace not only a continuous nozzle

1 surrounding the passage, but also a discontinuous
2 nozzle having two or more nozzle outlets partially
3 or entirely surrounding the passage.

4
5 The or each nozzle may be of a convergent-divergent
6 geometry internally thereof, and in practice the
7 nozzle is configured to give the supersonic flow of
8 transport fluid within the passage. For a given
9 steam condition, i.e. dryness, pressure and
10 temperature, the nozzle is preferably configured to
11 provide the highest velocity steam jet, the lowest
12 total pressure drop and the highest enthalpy between
13 the steam chamber and nozzle exit.

14
15 The condensation profile in the mixing chamber
16 determines the expansion ratio profile across the
17 nozzle. With relatively low working fluid
18 temperatures condensation is dominant, and the exit
19 pressure of the transport fluid nozzle is low. The
20 exit pressure of the transport fluid nozzle is
21 higher when the bulk temperature of the working
22 fluid is higher.

23
24 According to a third aspect of the present invention
25 a method of moving a working fluid includes
26 presenting a fluid mover to the working fluid,
27 the mover having a straight-through passage of
28 substantially constant cross section,
29 applying a substantially circumscribing stream
30 of a transport fluid to the passage through an
31 annular nozzle,

1 atomising the working fluid to form a dispersed
2 vapour and droplet flow regime with locally
3 supersonic flow conditions,
4 generating a supersonic condensation shock wave
5 within the passage downstream of the nozzle by
6 condensation of the transport fluid,
7 inducing flow of the working fluid through the
8 passage from an inlet to an outlet thereof, and
9 modulating the condensation shock wave to vary
10 the working fluid discharge from the outlet.

11

12 Preferably the modulating step includes modulating
13 the intensity of the condensation shock wave..
14 Alternatively or additionally the modulating step
15 includes modulating the position of the condensation
16 shock wave.

17

18 The bore profile immediately upstream of the nozzle
19 is preferably configured to encourage working fluid
20 atomisation. Preferably an instability in working
21 fluid flow is introduced immediately upstream of the
22 nozzle.

23

24 The or each nozzle is preferably optimally
25 configured to operate with a particular working
26 fluid, upstream wall contour profile and mixing
27 chamber geometry. The nozzles, upstream wall
28 contour profile and mixing chamber combination are
29 configured to encourage working fluid atomisation
30 creating a vapour/droplet mixed flow with local
31 supersonic flow conditions. This encourages the
32 formation of the downstream condensation shock wave,

1 by enhancing local turbulence, pressure gradient and
2 the momentum and heat transfer rate between the
3 transport and working fluids by maximising surface
4 contact between the fluids.

5
6 The or each nozzle is preferably configured to
7 operate with a particular working fluid, upstream
8 wall contour profile and mixing chamber to provide
9 an optimum nozzle exit pressure. Initial pressure
10 recovery due to transport fluid deceleration,
11 coupled with the downstream pressure drop due to
12 condensation, is used to ensure the nozzle expansion
13 ratio is adjusted to enhance atomisation of the
14 working fluid and momentum transfer.

15
16 The exit velocity from the or each nozzle may be
17 controlled by varying the transport fluid supply
18 pressure, the expansion ratio of the nozzle and the
19 condensation profile in the immediate region of the
20 mixing chamber. The nozzle exit velocities may be
21 controlled to enhance Momentum Flux Ratios M in the
22 immediate region of the mixing chamber, where M is
23 defined by the equation

$$24 \quad M \equiv \frac{(\rho_s \times U_s^2)}{(\rho_f \times U_f^2)}$$

25
26 where ρ = Fluid density

27 U = Fluid velocity

28 Subscript s represents transport fluid

29 Subscript f represents working fluid

30

1 In the present invention it has been found that an
2 optimum Momentum Flux Ratio M for the or each nozzle
3 lies in the range $2 \leq M \leq 70$. For example, when using
4 steam as the transport fluid, with a working fluid
5 with a high water content, M for the or each nozzle
6 lies in the range $5 \leq M \leq 40$.

7
8 The or each nozzle is configured to provide the
9 desired combination of axial, radial and tangential
10 velocity components. It is a combination of axial,
11 radial and tangential components which influence the
12 primary turbulent break-up (atomisation) of the
13 working fluid flow and the pressure gradient.

14
15 The interaction between the transport fluid and the
16 working fluid, leading to the atomisation of the
17 working fluid, is enhanced by flow instability.
18 Instability enhances the droplet stripping from the
19 contact surface of the core flow of the working
20 fluid. A turbulent dissipation layer between the
21 transport and working fluids is both fluidically and
22 mechanically (geometry) encouraged ensuring rapid
23 fluid core dissipation. The pseudo-vena contracta
24 is a resultant aspect of this droplet atomisation
25 region.

26
27 The internal walls of the flow passage upstream of
28 the or each nozzle may be contoured to provide a
29 combination of axial, radial and tangential velocity
30 components of the outer surface of the working fluid
31 core when it comes into contact with the transport
32 fluid. It is a combination of these velocity

1 components which inter alia influence the primary
2 turbulent break-up (atomisation) of the working
3 fluid and the pressure gradient when it comes into
4 contact with the transport fluid.

5
6 Under optimum operating conditions the
7 disintegration or atomisation of the working fluid
8 core is extremely rapid. The disintegration across
9 the whole bore will typically take place in the
10 mixing chamber within, but not limited to, a
11 distance approximately equivalent to $0.66D$
12 downstream of the nozzle exit. Under different non-
13 optimised operating conditions disintegration across
14 the whole bore of the mixing chamber, may still
15 occur within, but not limited to, a distance
16 equivalent to $1.5D$ downstream of the nozzle exit,
17 where D is the nominal diameter of the bore through
18 the centre of the fluid mover.

19
20 Recirculation occurs in the flow. The
21 recirculation is particularly dominant where
22 tangential velocity components of the transport
23 fluid are present. The radial pressure gradients
24 created within the mixing chamber are responsible
25 for this flow phenomenon which encourages complete
26 and rapid flow dispersion characteristics across the
27 bore.

28
29 This effect is also created when the pseudo-vena
30 contracta is partially established, i.e. vapour-
31 droplet flow is dominant along the mixing chamber
32 boundary. The localised pressure gradient draws

1 flow outwards, causing a region downstream of the
2 transport fluid nozzle exit, typically between 1
3 diameter and 2 diameters downstream, where the axial
4 flow component of the working fluid stagnates and
5 may even reverse briefly on the centre-line, i.e.
6 the centre of the flow region.

7

8 Recirculation has particular benefits in some
9 applications such as emulsification.

10

11 A series of nozzles with respective mixing chamber
12 sections associated therewith may be provided
13 longitudinally of the passage and in this instance
14 the nozzles may have different angular orientations,
15 for example decreasing from the first nozzle in a
16 downstream direction. Each nozzle may have a
17 different function from the other or others, for
18 example pumping, mixing, disintegrating or
19 emulsifying, and may be selectively brought into
20 operation in practice. Each nozzle may be
21 configured to give the desired effects upon the
22 working fluid. Further, in a multi-nozzle system by
23 the introduction of the transport fluid, for example
24 steam, phased heating may be achieved. This
25 approach may be desirable to provide a gradual
26 heating of the working fluid, enhanced atomisation,
27 pressure gradient profiling or a combinatory effect,
28 such as enhanced emulsification.

29

30 In addition the internal walls of the flow passage
31 immediately upstream of the or each nozzle exit may
32 be contoured to provide different degrees of

1 turbulence to the working fluid prior to its
2 interaction with the transport fluid issuing from
3 the or each nozzle.

4
5 The mixing chamber geometry is determined by the
6 desired and projected output performance and to
7 match the designed transport fluid conditions and
8 nozzle geometry. In this respect it will be
9 appreciated that there is a combinatory effect as
10 between the various geometric features and their
11 effect on performance, namely there is interaction
12 between the various design and performance
13 parameters having due regard to the defined function
14 of the fluid mover.

15
16 According to a fourth aspect of the present
17 invention a method of processing a working fluid
18 includes

19 presenting a fluid mover to the working fluid,
20 the fluid mover having a straight-through passage of
21 substantially constant cross section,

22 applying a substantially circumscribing stream
23 of a transport fluid to the passage through an
24 annular nozzle,

25 atomising the working fluid to form a dispersed
26 vapour and droplet flow regime with locally
27 supersonic flow conditions,

28 generating a supersonic condensation shock wave
29 within the passage downstream of the nozzle by
30 condensation of the transport fluid, the position of
31 the condensation shock wave remaining substantially
32 constant under equilibrium flow,

1 inducing flow of the working fluid through the
2 passage from an inlet to an outlet thereof, and
3 changing the position of the condensation shock
4 wave to vary the working fluid discharge from the
5 outlet.

6
7 Changing the position of the condensation shock wave
8 is preferably achieved by varying at least one of a
9 group of parameters, the group of parameters
10 including the inlet temperature of the working
11 fluid, the flow rate of the working fluid, the inlet
12 pressure of the working fluid, the outlet pressure
13 of the working fluid, the flow rate of a fluid
14 additive added to the working fluid, the inlet
15 pressure of a fluid additive added to the working
16 fluid, the outlet pressure of a fluid additive added
17 to the working fluid, the temperature of a fluid
18 additive added to the working fluid, the angle of
19 entry of the transport fluid to the passage, the
20 inlet temperature of the transport fluid, the flow
21 rate of the transport fluid, the inlet pressure of
22 the transport fluid, the internal dimensions of the
23 passage downstream of the nozzle, and the internal
24 dimensions of the passage upstream of the nozzle.

25
26 The term straight-through when used to describe a
27 passage encompasses any passage having a clear flow
28 path therethrough, including curved passages.

29
30 The fluid additive may be gaseous or liquid. The
31 fluid additive is not an essential element of the
32 invention, but in certain circumstances may be

1 beneficial. The fluid additive may comprise a
2 powder in dry form or suspended in a fluid.

3

4 The parameter varying step may include switching
5 between a plurality of transport fluids or between a
6 plurality of fluid additives.

7

8 The improvements of the present invention may be
9 employed to the fluid mover of the aforementioned
10 patent, and enhance its use in a variety of
11 applications as disclosed in the aforementioned
12 patent. These applications range from use as a
13 fluid processor, including pumping, mixing, heating,
14 homogenising etc, to marine propulsion, where the
15 mover is submersed within a body of fluid, namely
16 the sea or lake or other body of water. In its
17 application to fluid processing a variety of working
18 fluids may be processed and may include liquids,
19 liquids with solids in suspension, slurries, sludges
20 and the like. It is an advantage of the straight-
21 through passage of the mover that it can accommodate
22 material that might find its way into the passage.

23

24 The fluid mover of the present invention may also be
25 used for enhanced mixing, dispersion or hydration
26 and again the combination of the shearing mechanism,
27 droplet formation and presence of the condensation
28 shock wave provides the mechanism for achieving the
29 desired result. In this connection the fluid mover
30 may be used for mixing one or more fluids, one or
31 more fluids and solids in particulate form, for
32 example powders. The fluids may be in liquid or

1 gaseous form. It has been found that the use of the
2 present invention when mixing liquid with a powder
3 of particulate form results in a homogeneous
4 mixture, even when the powder is of material which
5 is difficult to wet, for example Gum Tragacanth
6 which is a thickening agent.

7
8 The treatment of the working fluid, for example
9 heating, dosing, mixing, dispersing, emulsifying etc
10 may occur in batch mode using at least one fluid
11 mover or by way in an in-line or continuous
12 configuration using one or more fluid movers as
13 required.

14
15 A further use to which the present invention may be
16 put is that of emulsification which is the formation
17 of a suspension by mixing two or more liquids which
18 are not soluble in each other, namely small droplets
19 of one liquid (inner phase) are suspended in the
20 other liquid(s) (outer phase). Emulsification may
21 be achieved in the absence of surfactant blends,
22 although they may be used if so desired. In
23 addition, due to the straight through nature of the
24 invention, there is no limitation on the particle
25 size that can be handled, allowing particle sizes up
26 to the bore size of the unit to pass through whilst
27 emulsification is taking place.

28
29 The fluid mover may also be employed for
30 disintegration, for example in the paper industry
31 for disintegration of paper pulp. A typical example
32 would be in paper recycling, where waste paper or

1 broken pieces are mixed with water and passed
2 through the fluid mover. A combination of the heat
3 addition, the high intensity shearing mechanism, the
4 low pressure region in the vapour-droplet flow and
5 the condensation shock wave both rapidly hydrates
6 the paper fibres, and macerates and disintegrates
7 the paper pieces into smaller sizes. Disintegration
8 down to individual fibres has been achieved in
9 tests. Similarly, the fluid mover could be used in
10 de-inking processes, where the heating and shearing
11 assist in the removal of ink from paper pulp as it
12 passes through the fluid mover.

13

14 The straight through aspect of the invention has the
15 additional benefit of offering very little flow
16 restriction and therefore a negligible pressure
17 drop, when a fluid is moved through it. This is of
18 particular importance in applications where the
19 fluid mover is located in a process pipe work and
20 fluid is pumped through it, such as the case, for
21 example, when the fluid mover of the present
22 invention is turned 'off' by the reduction or
23 stopping of the supply of transport fluid. In
24 addition, the straight through passage and clear
25 bore offers no impedance to cleaning 'pigs' or other
26 similar devices which may be employed to clean the
27 pipe work.

28

29 A detailed description of the energy transfer
30 mechanism, focussing on the momentum transfer
31 between the transport fluid and working fluid by an
32 enhanced shearing mechanism is best described with

1 reference to the accompanying drawings. By way of
2 example, eight embodiments of geometrical features
3 that may be employed to enhance this energy transfer
4 mechanism in accordance with the present invention
5 are described below with reference to the
6 accompanying drawings in which:

7

8 Figure 1 is a cross sectional elevation of a fluid
9 mover according to the present invention;

10 Figure 2 is a magnified view of the shearing
11 mechanism shown in Figure 1;

12 Figure 3 is a cross sectional elevation of a first
13 embodiment;

14 Figure 4 is a cross sectional elevation of a second
15 embodiment;

16 Figure 5 is a cross sectional elevation of a third
17 embodiment;

18 Figure 6 is a cross sectional elevation of a fourth
19 embodiment;

20 Figure 7 is a cross sectional elevation of a fifth
21 embodiment;

22 Figure 8 is a cross sectional elevation of a sixth
23 embodiment;

24 Figure 9 is a cross sectional elevation of a seventh
25 embodiment;

26 Figure 10 is a schematic section through the fluid
27 regime of the fluid mover of the present invention;

28 Figure 11 is a schematic drawing of the fluid mover
29 of the present invention in use;

30 Figure 12 is a schematic drawing showing pressure in
31 the fluid mover of the present invention under three
32 different operating conditions;

1 Figure 13 is a schematic drawing showing a section
2 through the fluid mover of the present invention and
3 the pressure distribution in the fluid mover under
4 two different condensation shock wave positions; and
5 Figures 14a and 14b are partial cross sectional
6 views through an eighth embodiment of the fluid
7 mover of the present invention.

8
9 Like numerals of reference have been used for like
10 parts throughout the specification.

11
12 Referring to Figure 1 there is shown a fluid mover
13 1, comprising a housing 2 defining a passage 3
14 providing an inlet 4 and an outlet 5, the passage 3
15 being of substantially constant circular cross
16 section.

17
18 The housing 2 contains a plenum 8 for the
19 introduction of a transport fluid, the plenum 8
20 being provided with an inlet 10. The distal end of
21 the plenum is tapered on and defines an annular
22 nozzle 16. The nozzle 16 being in flow communication
23 with the plenum 8. The nozzle 16 is so shaped as in
24 use to give supersonic flow.

25
26 In operation the inlet 4 is connected to a source of
27 a process or working fluid. Introduction of the
28 steam into the fluid mover 1 through the inlet 10
29 and plenum 8 causes a jet of steam to issue forth
30 through the nozzle 16. Steam issuing from the
31 nozzle 16 interacts with the working fluid in a
32 section of the passage operating as a mixing chamber

1 (3A). In operation the condensation shock wave 17
2 is created in the mixing chamber (3A).

3
4 In operation the steam jet issuing from the nozzle
5 occasions induction of the working fluid through the
6 passage 3 which because of its straight through
7 axial path and lack of any constrictions provides a
8 substantially constant dimension bore which presents
9 no obstacle to the flow. At some point determined
10 by the steam and geometric conditions, and the rate
11 of heat and mass transfer, the steam condenses
12 causing a reduction in pressure. The steam
13 condensation begins shortly before the condensation
14 shock wave and increases exponentially, ultimately
15 forming the condensation shock wave 17 itself.

16
17 The low pressure created shortly before and within
18 the initial phase of the condensation shock wave
19 results in a strong fluid induction through the
20 passage 3. The pressure rises rapidly within and
21 after the condensation shock wave. The condensation
22 shock wave therefore represents a distinct pressure
23 boundary/gradient.

24
25 The parametric characteristics of the steam coupled
26 with the geometric features of the nozzle, upstream
27 wall profile and mixing chamber are selected for
28 optimum energy transfer from the steam to the
29 working fluid. The first energy transfer mechanism
30 is momentum and mass transfer which results in
31 atomisation of the working fluid. This energy
32 transfer mechanism is enhanced through turbulence.

1 Figure 1 shows diagrammatically the break-up, or
2 atomisation sequence 18 of the working fluid core.

3

4 Figure 2 shows a magnified and exaggerated schematic
5 of the shearing and atomisation mechanism 18 of the
6 working fluid by the transport fluid. It is
7 believed that this mechanism can be broken down into
8 three distinct regions, each governed by established
9 turbulence mechanisms. The first region 20
10 experiences the first interaction between the
11 transport and working fluid. It is in this region
12 that Kelvin-Helmholtz instabilities in the surface
13 contact layer of the working fluid may start to
14 develop. These instabilities grow due to the shear
15 conditions, pressure gradients and velocity
16 fluctuations, leading to Rayleigh-Taylor ligament
17 break-up 24. Second order eddies within the fluid
18 surface waves may reduce in size to the scale of
19 Kolmogorov eddies 22. It is believed that the
20 formation of these eddies, in association with the
21 Rayleigh-Taylor ligament break-up, result in the
22 formation of small droplets 28 of the working fluid.

23

24 The droplet formation phases may also result in a
25 localised recirculation zone 26 immediately
26 following the ligament break-up region. This
27 recirculation zone may enhance the fluid atomisation
28 further by re-circulating the larger droplets back
29 into the high shear region. This recirculation, a
30 feature of the localised pressure gradient, is
31 controllable via the transport fluid's axial,
32 tangential and radial velocity and pressure

1 components. It is believed that this mechanism
2 enhances inter alia the mixing, emulsifying and
3 pumping capabilities of the fluid mover.

4

5 The primary break-up mechanism of the working fluid
6 core may therefore be enhanced by creating initial
7 instabilities in the working fluid flow.

8 Deliberately created instabilities in the transport
9 fluid/working fluid interaction layer encourage
10 fluid surface turbulent dissipation resulting in the
11 working fluid core dispersing into a liquid-ligament
12 region, followed by a ligament-droplet region where
13 the ligaments and droplets are still subject to
14 disintegration due to aerodynamic characteristics.

15

16 Referring now to Figure 3 the fluid mover of Figure
17 1 and 2 is provided with a contoured internal wall
18 in the region 19 immediately upstream of the exit of
19 the steam nozzle 16. The internal wall of the flow
20 passage 3 immediately upstream of the nozzle 16 is
21 provided with a tapering wall 30 to provide a
22 diverging profile leading up to the exit of the
23 steam nozzle 16. The diverging wall geometry
24 provides a deceleration of the localised flow,
25 providing disruption to the boundary layer flow, in
26 addition to an adverse pressure gradient, which in
27 turn leads to the generation and propagation of
28 turbulence in this part of the working fluid flow.
29 As this turbulence is created immediately prior to
30 the interaction between the working fluid and the
31 transport fluid, the instabilities initiated in
32 these regions enhance the Kelvin-Helmholtz

1 instabilities and hence ligament and droplet
2 formation as foreshadowed in the foregoing
3 description occurs more rapidly.

4
5 An alternative embodiment is shown in Figure 4.
6 Again, the fluid mover of Figure 1 and 2 is provided
7 with a contoured internal wall 19 of the flow
8 passage 3 immediately upstream of the nozzle 16.
9 The contoured surface in this embodiment is provided
10 by a diverging wall 30 on the bore surface leading
11 up to the exit of the steam nozzle 16, but the taper
12 is preceded with a step 32. In use, the step
13 results in a sudden increase in the bore diameter
14 prior to the tapered section. The step 'trips' the
15 flow, leading to eddies and turbulent flow in the
16 working fluid within the diverging section,
17 immediately prior to its interaction with the steam
18 issuing from the steam nozzle 16. These eddies
19 enhance the initial wave instabilities which lead to
20 ligament formation and rapid fluid cone dispersion.

21
22 The tapered diverging section 30 could be tapered
23 over a range of angles and may be parallel with the
24 walls of the bore. It is even envisaged that the
25 tapered section 30 may be tapered to provide a
26 converging geometry, with the taper reducing to a
27 diameter at its intersection with the steam nozzle
28 16 which is preferably not less than the bore
29 diameter.

30
31 The embodiment shown in Figure 4 is illustrated with
32 the initial step 32 angled at 90° to the axis of the

1 bore 3. As an alternative to this configuration,
2 the angle of the step 32 may display a shallower or
3 greater angle suitable to provide a 'trip' to the
4 flow. Again, the diverging section 30 could be
5 tapered at different angles and may even be parallel
6 to the walls of the bore 3. Alternatively, the
7 tapered section 30 may be tapered to provide a
8 converging geometry, with the taper reducing to a
9 diameter at its intersection with the steam nozzle
10 16 which is preferably not less than the bore
11 diameter.

12

13 Figures 5 to 8 illustrate examples of alternative
14 contoured profiles. All of these are intended to
15 create turbulence in the working fluid flow
16 immediately prior to the interaction with the
17 transport fluid issuing from the nozzle 16.

18

19 The embodiments illustrated in Figures 5 and 6
20 incorporate single or multiple triangular cross
21 section grooves 34, 36 immediately prior to a
22 tapered or parallel section 30, which is in turn
23 immediately prior to the exit of the steam nozzle
24 16.

25

26 The embodiments illustrated in Figures 7 and 8
27 incorporate single or multiple triangular 38 and/or
28 square 40 cross section grooves a short distance
29 upstream of the exit of the steam nozzle 16. These
30 embodiments are illustrated without a tapering
31 diverging section after the grooves.

32

1 Although Figures 1 to 8 illustrate several
2 combinations of grooves and tapering sections, it is
3 envisaged that any combination of these features, or
4 any other groove cross-sectional shape may be
5 employed.

6
7 The tapered section 30 and/or the step 32 and/or the
8 grooves 34, 36, 38, 40 may be continuous or
9 discontinuous in nature around the bore. For
10 example, a series of tapers and/or grooves and/or
11 steps may be arranged around the circumference of
12 the bore in a segmented or 'saw tooth' arrangement.

13
14 The nature of the flow regime in the fluid mover of
15 the present invention is described in more detail
16 below, with reference to Figure 10.

17
18 The transport fluid, usually steam 80, enters
19 through nozzle 16 at supersonic velocity. Wherever
20 the term steam is used, it is to be understood that
21 the term can also be applied to other transport
22 fluids. The working fluid, usually liquid 82, flows
23 at a subsonic velocity into the inlet 4. At the
24 nozzle 16 there is a subsonic liquid core 84 which
25 is bounded by a generally rough or turbulent conical
26 interface with the steam 80 and the region of
27 dispersion 88. As the steam 80 exits the nozzle 16
28 it exhibits local shock and expansion waves 86 and
29 forms a pseudo vena contracta 90. The accelerated
30 region of dispersion 88 (or dissociation) of the
31 liquid core flows at a locally supersonic velocity
32 into the vapour-droplet region 92, in which the

1 vapour is steam and the droplets are the working
2 fluid. Condensation takes place in the supersonic
3 condensation zone 94 and the subsonic condensation
4 zone 96. The condensation shock wave 17 is produced
5 when the condensation, which initiates in the
6 locally supersonic low density region 94, reaches an
7 exponential rate. The zone 96 immediately after the
8 condensation shock wave 17 has a considerably higher
9 density and is hence subsonic. The condensation
10 shock wave 17 thus defines the interface between
11 these two densities.

12
13 In the liquid phase 98 beyond the condensation zone
14 96 there are small vapour bubbles. The position of
15 the condensation shock wave is controllable over a
16 distance L by adjustment of one of the plurality of
17 parameters described herein.

18
19 The break-up and dispersion of the primary liquid
20 core produces a droplet vapour region. Any liquid
21 instabilities on the primary liquid cone surface 18
22 are amplified to form 'waves'. These waves are
23 further elongated to form ligaments that undergo
24 Rayleigh-Taylor break-up, resulting in the formation
25 of small droplets 28, separated ligaments 24 and
26 larger droplets.

27
28 The secondary region 24 is thus characterised by the
29 rapid increase in the effective fluid surface area.
30 These droplets 28, of varying size, are then subject
31 to several aerodynamic and thermal effects which
32 ultimately result in their break up to sizes

1 characteristic with the turbulence levels in this
 2 region. This results in the vapour-droplet region
 3 which defines the flow regime within the fluid
 4 mover.

5
 6 The thickness of the viscous sub layer, comprising
 7 the high speed vapour/gas and the locally entrained
 8 liquid in droplet or ligament form, increases
 9 downstream to ultimately extend across the entire
 10 bore. The turbulence within this region arises from
 11 shear (velocity gradient) and eddies (large scale to
 12 Kolmogorov scale), as the flow is essentially of a
 13 vapour-droplet consistency. High levels of shear
 14 exist in the gas/liquid interface.

15
 16 A large amount of energy is transferred in this
 17 secondary region 24 as a result of further particle
 18 break-up. Mass transfer takes place as the shear
 19 forces and thermal discontinuities result in the
 20 droplets becoming ever smaller. The pressure
 21 reduces and droplets are evaporated in order to
 22 maintain equilibrium in the flow. Heat transfer
 23 takes place as equilibrium conditions are reached,
 24 ensuring that liquid vapour phase transitions and
 25 the inverse transitions all occur within the mixing
 26 section of the passage 3. In the secondary region
 27 there is a very rapid increase in the void fraction

$$28 \quad \alpha = \frac{A_g}{A_{Tot}}$$

29
 30 where α = void fraction

31 A_g = area of gas phase (dispersion cone)

32 A_{Tot} = total area of pump flow

1
2 Thus the rapid increase in specific volume as the
3 liquid droplets/ligaments are further dispersed,
4 will obviously result in a larger void fraction.
5 Subsequently as the flow conditions begin to
6 approach a state of equilibrium, and due to the
7 geometry within the mixing chamber, the vapour flow
8 is encouraged to follow a condensation profile
9 towards an aerodynamic and condensation shock wave,
10 which is a region of non-equilibrium and entropy
11 production.

12
13 The condensation shock wave arises from the rapid
14 change from a two-phase fluid mixture to a
15 substantially single phase fluid with complete
16 condensation of the vapour phase. Since there is no
17 unique sonic speed in vapour droplet mixtures, non-
18 equilibrium and equilibrium exchanges of momentum,
19 mass and energy can occur. In order to achieve a
20 normal condensation shock wave, the velocity of the
21 vapour mixture within the mixing chamber has to be
22 maintained above a certain value defined as the
23 equilibrium sonic speed. For conditions where the
24 vapour velocity is greater than the frozen sonic
25 speed, or where the velocity of the vapour mixture
26 is between the equilibrium and frozen sonic speed,
27 this results in a dispersed or partially dispersed
28 condensation shock wave. These two asymptotic sonic
29 speeds are:

30

1 a_e = equilibrium shock speed. This is the speed at
 2 which every fluid is in its correct equilibrium
 3 condition, i.e. vapour is vapour, liquid is liquid
 4

5 a_f = frozen shock speed. This occurs primarily due
 6 to a 'lag' effect, so that some fluids are not in
 7 their correct phase, for example the local
 8 temperature and pressure dictate that a vapour
 9 should be turning to liquid, but the phase change
 10 has not happened.

11

12 a_f and a_e are defined as:

13

$$14 \quad a_f = \sqrt{\gamma \cdot R_v \cdot T_s}$$

15

$$16 \quad a_e = \sqrt{\frac{\chi \cdot \gamma \cdot R_v \cdot T_s}{\gamma \left[1 - \frac{R_v \cdot T_s}{h_{fg}} \left(2 - \frac{c \cdot T_s}{h_{fg}} \right) \right]}}$$

17

18 where

19

$$20 \quad c = Cp_v + \frac{\left(\frac{1 - \varepsilon}{\varepsilon} \right)}{Cp_f}$$

21 γ = Ratio of specific heats (the vapour and the
 22 fluid)

23 R_v = Gas constant for vapour phase (steam)

24 T_s = Saturation temperature of mixture (vapour and
 25 fluid)

26 Cp = Specific heat

27 H_{fs} = Latent heat of vapourisation

28 χ = Initial vapour quality

29 ε = Vapour fraction (gas/liquid)

30

1 Subscript v, represents vapour (steam)

2 Subscript f, represents fluid (e.g. liquid)

3

4 Frozen flow arises when the interface transport of
5 mass, momentum and energy between the vapour phase
6 and liquid droplets is frozen completely, i.e. the
7 liquid droplets do not take part in the fluid
8 mechanical processes.

9

10 Equilibrium flow arises when the velocity and
11 temperature of the vapour and liquid are in
12 equilibrium, and the partial pressure due to the
13 vapour is equal to the saturation pressure
14 corresponding to the temperature of the flow.

15

16 The secondary flow regime can better be understood
17 by further subdivision into three sub-regions.

18

19 The first sub-region of the secondary flow regime is
20 the droplet break-up sub-region. Just as in the
21 primary zone, where the liquid core is stripped to
22 form the droplet-vapour zone, with the stripping of
23 the ligaments and droplets on the surface, so in the
24 secondary region there is further break-up or
25 dispersion of these separated ligaments, and also
26 the break-up of droplets whose characteristics are
27 unstable in the turbulent flow regime. The dominant
28 mechanism responsible for the break-up in the
29 secondary region is the acceleration of droplets or
30 momentum transfer due to the slip velocity between
31 vapour and liquid. The injection velocity of the
32 vapour in the present invention is important to this

1 functional aspect of the flow regime. If required,
 2 multiple nozzles staggered downstream may be used to
 3 encourage this aspect. Other parameters such as
 4 nozzle angle and mixing chamber geometry can be
 5 selected to establish favourable flow conditions.

6
 7 Typical break-up mechanisms in this region are
 8 dependant on the local velocity slip conditions and
 9 the respective working fluid properties. These are
 10 gathered into a dimensionless number referred to as
 11 the aerodynamic Weber number defined as:

$$12 \quad We = \frac{\rho_v \cdot (U_f - U_v)^2 \cdot D_f}{\sigma_f}$$

14

15 where

16 ρ_v = Density of vapour

17 U = Velocity

18 D_f = Hydraulic diameter of fluid

19 σ_f = Surface tension of fluid

20

21 Typical break-up mechanisms found in the fluid mover
 22 of the present invention are vibrational break-up,
 23 which can be found with ligaments and droplets whose
 24 characteristic length is greater than the stable
 25 length; catastrophic break-up, which is especially
 26 dominant in the liquid-vapour shear layer where We
 27 ≥ 350 ; wave crest stripping, which occurs where
 28 droplets, due to their size, experience large
 29 aerodynamic forces causing ellipsoidal shapes,
 30 typically where $We \geq 300$; and short stripping, which
 31 is the dominant break-up mechanism where daughter

1 and satellite droplets have been formed following
2 the ligament stripping and dispersion, typically
3 where $We \geq 100$.

4
5 The turbulent motion of the surrounding gas,
6 especially where the Reynold numbers are large ($Re >$
7 10^4), as is usually the case in the present
8 invention, results in large amounts in local energy
9 dissipation and accompanying droplet break-up. The
10 fluctuating dynamic pressures resulting from these
11 turbulent fluctuations are dominant in droplet
12 break-up but very importantly it is this energy that
13 ensures extremely effective dispersion and mixing of
14 the fluids in the flow.

15
16 Turbulent pressure fluctuations result in shear
17 forces capable of rupturing fibres or filaments and
18 dissipating powder lumps or similar solid or semi-
19 solid matter. In the primary region energy, mass
20 and momentum transfer takes place through a more
21 distinct boundary, associated with the liquid cone
22 dispersion. In the secondary break-up region this
23 transfer is directly related to the turbulence
24 intensity, closely associated with the turbulent
25 dissipation region in the flow.

26
27 The thermal boundary layer, although similar in
28 characteristic to the turbulent dissipation
29 sublayer, represents the effective boundary where
30 evaporation/condensation and energy transfer occur
31 in either an equilibrium state or 'frozen' state.

32

1 Interfacial transport, which begins within the
2 primary cone dissipation, continues into the
3 secondary vapour-droplet region and is characterised
4 by distinct mechanisms enhanced within the fluid
5 mover of the invention through vapour introduction
6 conditions, dependent on pressure and velocity, the
7 physical geometry of the steam nozzles and the
8 mixing chamber geometry. This results in a
9 continuous surface renewal process, which together
10 with the turbulence results in a series of renewed
11 eddies of various scales. These eddies create
12 bursts arising from the interface of the liquid
13 vapour and the waves formed on ligaments and
14 droplets which are undergoing further break-up.
15 These bursts have a period which is a function of
16 the interfacial shear velocity. These bursts
17 greatly encourage mixing, heat transport and
18 emulsification (droplet size reduction).

19

20 The second sub-region of the secondary flow regime
21 is the subcooled vapour-droplet region. As the
22 vapour mixture flows through the fluid mover of the
23 invention its velocity profile is adjusted through
24 fluidic interaction as well as the static pressure
25 gradient which gradually rises due to general
26 deceleration of the flow. This controlled diffusion
27 of the supersonic flow, balance of natural fluidic
28 and thermodynamic interactions coupled with discrete
29 geometry results in a vapour-droplet state where
30 sub-cooled droplets exist within a vapour dominant
31 phase. The sub-cooled state of this frozen mixture
32 increases until droplet nucleation, and hence

1 condensation, begins to occur very rapidly. The
2 point of maximum sub-cooling (Wilson point)
3 determines the point at which the nucleation rate,
4 which is closely dependent on sub-cooling because of
5 the available surface area for condensation, begins
6 to occur very rapidly, and reaches near exponential
7 rates. The vapour-droplet region within the fluid
8 mover of the invention thus is able to attain near
9 thermodynamic equilibrium within a very short zone.

10

11 The fluid mover of the invention makes special use
12 of geometric conditions created through both
13 geometry and pseudo geometric conditions to ensure
14 the flow conditions upstream of the critical
15 subcooled state deviate from the thermodynamic
16 equilibrium. This ensures maintenance of the
17 desired vapour-droplet region with its desirable
18 droplet break-up, particle dispersion and heat
19 transfer effects.

20

21 The rapid acceleration of the fluid from the primary
22 fluid cone into the vapour region results in an
23 expansion wave, which similarly represents a
24 thermodynamic discontinuity and allows the vapour
25 droplet region to deviate markedly from equilibrium
26 and enter a 'frozen' flow condition.

27

28 Figure 9 shows an embodiment of the fluid mover of
29 the invention in which the geometry of the passage 3
30 has a mixing chamber 3A with a divergent region 50,
31 a constant diameter region 52 and a re-convergence
32 profile region 54. The constant through bore is

1 maintained, but the embodiment of Fig 9 promotes
2 this expansion and non-equilibrium. This offers
3 excellent particle dispersion, and good flow,
4 pressure head and suction conditions.
5

6 The third sub-region of the secondary flow regime is
7 the condensation shock region. As a result of the
8 sub-cooled vapour-droplet flow regime within the
9 fluid mover, the point at which exponential
10 condensation begins to occur defines the
11 condensation shock wave boundary. The mixture
12 conditions upstream of the condensation shock wave
13 determine the nature of the pressure and temperature
14 recovery experienced within the fluid mover.
15

16 The phase change across the condensation shock wave
17 obviously results in heat removal from the vapour
18 phase, although there will be an entropy increase
19 across the condensation shock wave. The ideal
20 operating conditions in the fluid mover of the
21 invention coincide with the formation of a normal
22 condensation shock wave, referred to as being
23 discrete, due to its relatively rapid and hence
24 negligible size measured along the X-axis.
25

26 The nature of the fluid flow in the fluid mover of
27 the present invention may better be understood by
28 reference to Figure 12, which shows the distribution
29 of pressure p in the fluid mover over length x along
30 the axis. Reference is made to the two shock
31 speeds, a_e and a_f , defined earlier.
32

1 Fig. 12a shows condition A and represents the
2 situation where $U_{\text{mixture}} > a_e$, where U_{mixture} is the
3 velocity of the vapour/droplet mixture.
4

5 This results in a normal condensation shock wave,
6 with a fairly rapid rise in pressure across the
7 condensation shock wave. The resulting exit
8 pressure is higher than the local pressure at the
9 steam inlet into the bore of the fluid mover.
10

11 Fig. 12b shows condition B and represents the
12 situation where $a_f > U_{\text{mixture}} > a_e$. In this case the
13 mixture velocity is higher than the equilibrium
14 shock speed but less than the frozen shock speed.
15 In this condition the condensation shock wave is
16 fully dispersed resulting in a much more gradual
17 pressure rise across the condensation shock wave.
18

19 Fig. 12c shows condition C and represents the
20 situation where $U_{\text{mixture}} > a_f$. In this condition an
21 'unstable' condition arises, with the steam not
22 fully condensing. This is referred to as a
23 partially dispersed condensation shock wave. This
24 results in the start of the formation of a
25 condensation shock wave (with a reasonably steep
26 pressure gradient), the condensation shock wave
27 formation 'stalling', and then restarting again.
28 However, it has been found that the final resulting
29 exit pressure is often higher than for either
30 Condition A or Condition B.
31

1 There are several mechanisms for determining the
2 state of the flow regime in the fluid mover, and
3 using this information in a control system to
4 provide the flow regime that best meets the demands
5 of the application. For example one can measure the
6 temperature at a particular point along the length
7 of the mixing chamber, to determine the existence of
8 a vapour-droplet region. Such a method is non-
9 intrusive since the mixer wall can be of thin
10 section allowing a rapid response to the change in
11 conditions. Multiple temperature probes spaced
12 downstream of one another can be used to monitor the
13 position of the condensation shock wave, as well as
14 to determine the state of the condensation shock
15 wave profile.

16
17 As a further example the use of pressure sensors
18 allows the condensation shock wave position to be
19 determined.

20
21 With reference to Figures 13 and 14 there is shown a
22 method of using a series of pressure sensors to
23 detect the position of the condensation shock wave
24 in the mixing chamber. When the condensation shock
25 wave 17 is in the position 17A indicated by Case 1,
26 i.e. in the convergent profile portion 3C of the
27 passage 3, the pressure profile is shown with the
28 reference numeral 101. When the condensation shock
29 wave 17 is in the position 17B indicated by Case 2,
30 i.e. in the uniform profile portion 3B of the
31 passage 3, the pressure profile is shown with the
32 reference numeral 102. Pressure sensors P1, P2 and

1 P3 in the passage 3 can be used to measure the
2 pressure at three points 103, 104, 105 along the
3 passage. The pressure measurements at these points
4 can be used to determine the position of the
5 condensation shock wave 17. Depending on the flow
6 profile required, one or more parameters, as
7 described hereinbefore, can be changed to alter the
8 flow profile and the position of the condensation
9 shock wave 17.

10

11 Figure 14a shows a typical pressure sensor, although
12 it is to be understood that this is not limiting,
13 and any suitable pressure sensor or measuring device
14 may be used. This method of measuring pressures in
15 the mixing chamber is especially suited for
16 condensation shock wave detection, since the
17 measurement technique only needs to measure a change
18 in pressure rather than being calibrated to measure
19 accurate values.

20

21 The mixing chamber 3A is sleeved with a thin walled
22 inner sleeve 107 of suitable material, such as
23 stainless steel. A thin layer of oil 108 fills the
24 gap between the sleeve 107 and the inner wall 106 of
25 the mixing chamber 3A. The pressure sensor P1 is
26 located through the wall 106 of the mixing chamber
27 and is in contact with the oil 108. When the
28 pressure inside the mixing chamber 3A changes, the
29 sleeve 107 expands or contracts a small amount,
30 thereby increasing or decreasing the pressure in the
31 oil 108, which is then detected by the pressure
32 sensor P1.

1
2 In the embodiment of Figure 14b the sleeve 107 is
3 segmented so that the oil is separated by walls 109
4 fixed to the sleeve. This results in separate
5 individual chambers of oil 108A, 108B, each with
6 their own pressure sensor P1, P2. A number of
7 separate chambers and pressure sensors may be
8 arranged along the wall 106 of the mixing chamber
9 3A.

10
11 The advantage of this instrumentation method is that
12 the sleeve 107 provides a clean inner bore, free of
13 any crevices or other features in which working
14 fluid or other transported material can become
15 trapped. This is of particular relevance for use in
16 the food industry. In addition, the pressure sensor
17 P1 is free from contamination, suffers no wear or
18 abrasion, and does not become blocked.

19
20 A further possible way of monitoring the
21 condensation shock wave is by the use of acoustic
22 signatures. Due to the density variation in the
23 mixer, even during powder addition, it is possible
24 to determine the 'state' of flow which is an
25 indication of vapour flow, and hence the condition
26 of having a condensation shock wave. The mechanisms
27 for determining the state of the flow regime in the
28 fluid mover may of course be combined.

29
30 Figure 11 shows an embodiment of the fluid mover 1
31 with various control means for controlling the
32 parameters of the flow. The inlet 4 is in fluid

1 communication with a working fluid valve 66 which
2 can be used to control the flow rate and/or inlet
3 pressure of the working fluid. A heating means or
4 cooling means (not shown) may be provided upstream
5 or downstream of the valve 66 to control the inlet
6 temperature of the working fluid. The outlet 5 is
7 in fluid communication with an optional working
8 fluid outlet valve 68 which can be used to control
9 the outlet pressure of the working fluid.

10

11 A transport fluid source 62, such as a steam
12 generator, is controllable to provide transport
13 fluid through the transport passage 64 to the plenum
14 8. The source 62 can be used to control the inlet
15 temperature and/or the flow rate and/or the inlet
16 pressure of the transport fluid.

17

18 The nozzle or nozzles 16 may be mounted for
19 adjustable movement such that a nozzle angle control
20 means (not shown) can be used to control the angle
21 of entry of the transport fluid to the passage.

22

23 The internal dimensions of the passage downstream of
24 the nozzle 16 can be adjusted by means of moveable
25 wall sections 60, which can alter the mixing chamber
26 wall profile between convergent, parallel and
27 divergent at a plurality of sections along the
28 mixing chamber 3A.

29

30 An additive fluid source 70 may be provided to add
31 one or more fluids to the working fluid. An
32 additive fluid valve 72 can be used to control the

1 flow rate of the additive fluid, including to switch
2 the flow on or off as appropriate. Separate heating
3 means may be provided for the additive fluid, which
4 may be a heated liquid, a gas such as steam or a
5 mixture. The additive may be a powder, and may be
6 introduced through a valve means from a secondary
7 hopper.

8
9 Control means such as a microprocessor may be
10 provided to control some or all of the parameters
11 described above as appropriate. The control means
12 can be linked to the condensation monitoring
13 devices, such as the pressure sensors P1, P2, P3
14 which monitor the condensation shock wave, or any
15 other sensor means eg temperature or acoustic
16 sensors.

17
18 The versatility of the fluid mover of the present
19 invention allows it to be applied in many different
20 applications over a wide range of operating
21 conditions. Two of these applications will now be
22 described, by way of example, to illustrate the
23 industrial applicability of the fluid mover of the
24 present invention.

25
26 The first of the applications is a method of
27 activating starch. The nature of the energy
28 transfer between the transport fluid and the working
29 fluid affords significant advantages for use in
30 starch activation. Due to the intimate mixing
31 between the hot transport fluid and the working
32 fluid, very high heat transfer rates between the

1 fluids are achieved resulting in rapid heating of
2 the working fluid. In addition, the high energy
3 intensity within the unit, especially the high
4 momentum transfer rates between the steam and
5 working fluid result in high shear forces on the
6 working fluid. It is therefore this combination of
7 heat and shear that result in enhanced starch
8 activation.

9
10 The fluid mover may be incorporated in either a
11 batch or a single pass fluid processing
12 configuration. One or more fluid movers may be used,
13 possibly mounted in series in a single pipeline
14 configuration. A single fluid mover may pump, heat,
15 mix, and activate the starch, or a separate pump may
16 be used to pass the working fluid through the fluid
17 mover. Alternatively, two or more fluid movers may
18 be used in series, each fluid mover may be
19 configured and optimized to carry out different
20 roles. For example, one fluid mover may be
21 configured to pump and mix (and do some initial
22 heating) and a second fluid mover mounted in series
23 down stream of the first, optimized to heat.

24
25 The energy intensity within the fluid mover is
26 controllable. By controlling the flow rates of the
27 steam and/or the working fluid, the intensity can be
28 reduced to allow slow heating of the working fluid,
29 and provide a much lower shear intensity. This could
30 be used, for example, to provide gentle heating of
31 the working fluid to maintain a batch of working

1 fluid at a constant temperature without causing any
2 shear thinning.

3

4 This method may also be employed for entraining,
5 mixing in, dispersing and dissolving other hard-to-
6 wet powders commonly employed in the food industry,
7 such as pectins. Pectins are typically used to
8 thicken foods or form gells, and are activated by
9 heat. Some pectins form thermoreversible gels in the
10 presence of calcium ions whereas others rapidly form
11 thermally irreversible gels in the presence of
12 sufficient sugars. The intense mixing, agitation,
13 shear and heating afforded by the Fluid Mover
14 enhances these gelling processes.

15

16 By way of example only, a fluid mover has been used
17 to pump, mix, homogenise, heat (cook) and activate
18 the starch in the manufacture of a 65kg batch of
19 tomato based sauce. Conventional processing required
20 the sauce to be heated to 85°C to activate the
21 starch. It was found, using the fluid mover to mix,
22 heat and process the sauce, that the starch was
23 activated at the much lower batch temperature of
24 70°C. Combining this saving in heating requirement
25 with the highly efficient mixing and heating
26 afforded by the fluid mover, the overall process
27 time was reduced by up to 95% over the conventional
28 tank heating and stirring method.

29

30 It has also been found that the Fluid Mover
31 activates a higher percentage of the starch present
32 in the mix than conventional methods. It is not

1 uncommon with food mixes containing highly modified
2 starches for a large percentage (greater than 50%)
3 of the starch to sometimes remain inactivated.
4 Activating a higher percentage of the starch
5 provides an obvious commercial advantage of reducing
6 the amount of starch that has to be added to a mix
7 to achieve a target viscosity. A similar effect has
8 been observed with the (relatively) expensive
9 pectin. Reducing the amount of pectin that has to be
10 added to a mix provides a significant cost saving to
11 the process.

12
13 This method may alternatively be employed in the
14 brewing industry. The brewing process requires the
15 rapid mixing, heating and hydration of ground malt,
16 known as grist, and activation of the starch. It has
17 been found that this can be achieved using the
18 method described in this invention, with the
19 additional advantages of maintaining the integrity
20 of both the enzymes and the husks of the grist.
21 Maintaining integrity of the enzymes in the mix is
22 important as they are required to convert the starch
23 to sugar in a later process, and similarly, the
24 husks are required to be of a particular size to
25 form an effective filter cake in a later Lauter
26 filtration process.

27
28 The second application offered by way of example is
29 a method of enhancing bioethanol (biofuel)
30 production using the fluid mover of the present
31 invention. The nature of the energy transfer
32 between the steam and the working fluid affords

1 significant advantages for use in bioethanol
2 production. Due to the intimate mixing between the
3 hot transport fluid (steam) and the working fluid,
4 very high heat transfer rates between the fluids are
5 achieved resulting in rapid heating of the working
6 fluid. In addition, the high energy intensity within
7 the unit, especially the high momentum transfer
8 rates between the steam and working fluid result in
9 high shear forces on the working fluid.

10

11 Two or more fluid movers may be used in series, each
12 fluid mover may be configured and optimized to carry
13 out different roles. For example, one fluid mover
14 may be configured to pump and mix (and do some
15 initial heating) and a second fluid mover mounted in
16 series down stream of the first, optimized to heat
17 and macerate.

18

19 Utilising the method described in this invention,
20 the process of mixing, heating, hydrating and
21 macerating the carbohydrate polymers in the biomass
22 can be achieved more rapidly and efficiently than
23 conventional methods. Utilising the high shear and
24 the presence of shockwave allows the active chemical
25 or biological components to be intimately mixed with
26 the carbohydrate polymers more efficiently,
27 enhancing the contact through pulping of the plant
28 matter as it begins to breakdown. Although the
29 method described in this invention utilizes high
30 temperature and high shear, it is still suitable for
31 use in an Enzymatic Hydrolysis process without
32 damage to the enzymes.

1

2 The shape of the fluid mover of the present
3 invention may be of any convenient form suitable for
4 the particular application. Thus the fluid mover of
5 the present invention may be circular, curvilinear
6 or rectilinear, to facilitate matching of the fluid
7 mover to the specific application or size scaling.
8 The enhancements of the present invention may be
9 applied to the fluid mover in any of these forms.

10

11 The fluid mover of the present invention thus has
12 wide applicability in industries of diverse
13 character ranging from the food industry at one end
14 of the chain to waste disposal at the other end.

15

16 The present invention when applied to the fluid
17 mover of the aforementioned patent affords
18 particularly enhanced emulsification and
19 homogenisation capability. Emulsification is also
20 possible with the deployment of the fluid mover of
21 the present invention on a once-through basis thus
22 obviating the need for multi-stage processing. In
23 this context also the mixing of different liquids
24 and/or solids is enhanced by virtue of the improved
25 shearing mechanism which affects the necessary
26 intimacy between the components being brought
27 together as exemplified heretofore.

28

29 The localised turbulence within the working fluid
30 dispersion region provides rapid mixing, dispersion
31 and homogenisation of a range of different fluids
32 and materials, for example powders and oils.

1

2 The heating of fluids and/or solids can be effected
3 by the use of the present invention with the fluid
4 mover by virtue of the use of steam as the transport
5 fluid and of course in this respect the invention
6 has multi-capability in terms of being able to pump,
7 heat, mix and disintegrate etc.

8

9 The fluid mover of the present invention may be
10 utilised, for example, in the essence extraction
11 process such as decaffeination. In this example the
12 fluid mover may be utilised to pump, heat, entrain,
13 hydrate and intimately mix a wide range of aromatic
14 materials with a liquid, usually water.

15

16 The vapour-droplet flow region of the present
17 invention provides a particular advantage for the
18 hydration of powders. Even extremely hard-to-wet
19 hydrophilic powders, for example Guar gum, may be
20 entrained and dispersed into a fluid medium within
21 this vapour-droplet region.

22

23 As has been disclosed above, the fluid mover of the
24 present invention possesses a number of advantages
25 in its operational mode and in the various
26 applications to which it is relevant. For example
27 the 'straight-through' nature of the fluid mover
28 having a substantially constant cross section, with
29 the bore diameter never reducing to less than the
30 bore inlet, means that not only will fluids
31 containing solids be easily handled but also any
32 rogue material will be swept through the mover

1 without impedance. The fluid mover of the present
2 invention is tolerant of a wide range of particulate
3 sizes and is thus not limited as are conventional
4 ejectors by the restrictive nature of their physical
5 convergent sections.

6

7 Modifications and improvements may be incorporated
8 without departing from the scope of the invention as
9 defined in the appended claims.

CLAIMS:

- 1 1. A fluid mover comprising:
2 a hollow body provided with a straight-through
3 passage of substantially constant cross section with
4 an inlet at one end of the passage and an outlet at
5 the other end of the passage for the entry and
6 discharge respectively of a working fluid;
7 a nozzle substantially circumscribing and
8 opening into said passage intermediate the inlet and
9 outlet ends thereof;
10 an inlet communicating with the nozzle for the
11 introduction of a transport fluid; and
12 a mixing chamber being formed within the
13 passage downstream of the nozzle;
14 wherein the nozzle internal geometry and the
15 bore profile of the passage immediately upstream of
16 the nozzle exit are so disposed and configured to
17 optimise the energy transfer between the transport
18 fluid and working fluid that in use through the
19 introduction of transport fluid the working fluid or
20 fluids are atomised to form a dispersed
21 vapour/droplet flow regime with locally supersonic
22 flow conditions within a pseudo-vena contracta,
23 resulting in the creation of a supersonic
24 condensation shock wave within the downstream mixing
25 chamber by the condensation of the transport fluid.
26
27 2. The fluid mover according to Claim 1, wherein
28 the passage is a substantially circular passage and
29 the nozzle is an annular nozzle substantially
30 circumscribing the passage.

1

2 3. The fluid mover according to either preceding
3 claim, wherein the nozzle is of a convergent-
4 divergent geometry internally thereof.

5

6 4. The fluid mover according to Claim 4, wherein
7 the nozzle is configured to give the supersonic flow
8 of transport fluid within the passage.

9

10 5. The fluid mover according to any preceding
11 claim, wherein the bore profile of the passage
12 immediately upstream of the nozzle is configured to
13 encourage working fluid atomisation.

14

15 6. The fluid mover according to any preceding
16 claim and comprising:

17 a plurality of nozzles substantially
18 circumscribing and opening into said passage
19 intermediate the inlet and outlet ends thereof;
20 a plurality of inlets, each inlet communicating
21 with a respective nozzle for the introduction of a
22 transport fluid; and

23 a plurality of mixing chambers, each mixing
24 chamber being formed within the passage downstream
25 of a respective nozzle.

26

27 7. A method of moving a working fluid, the method
28 comprising the steps of:

29 presenting a fluid mover to the working fluid,
30 the mover having a straight-through passage of
31 substantially constant cross section;

1 applying a substantially circumscribing stream
2 of a transport fluid to the passage through an
3 annular nozzle;

4 atomising the working fluid to form a dispersed
5 vapour and droplet flow regime with locally
6 supersonic flow conditions;

7 generating a supersonic condensation shock wave
8 within the passage downstream of the nozzle by
9 condensation of the transport fluid;

10 inducing flow of the working fluid through the
11 passage from an inlet to an outlet thereof; and

12 modulating the condensation shock wave to vary
13 the working fluid discharge from the outlet.

14

15 8. The method of Claim 7, wherein the modulating
16 step includes modulating the intensity of the
17 condensation shock wave.

18

19 9. The method of either Claim 7 or Claim 8,
20 wherein the modulating step includes modulating the
21 position of the condensation shock wave.

22

23 10. The method of any of Claims 7 to 9, further
24 comprising the step of introducing an instability in
25 working fluid flow immediately upstream of the
26 nozzle.

27

28 11. A method of processing a working fluid, the
29 method comprising the steps of:

30 presenting a fluid mover to the working fluid,
31 the fluid mover having a straight-through passage of
32 substantially constant cross section;

1 applying a substantially circumscribing stream
2 of a transport fluid to the passage through an
3 annular nozzle;

4 atomising the working fluid to form a dispersed
5 vapour and droplet flow regime with locally
6 supersonic flow conditions;

7 generating a supersonic condensation shock wave
8 within the passage downstream of the nozzle by
9 condensation of the transport fluid, the position of
10 the condensation shock wave remaining substantially
11 constant under equilibrium flow;

12 inducing flow of the working fluid through the
13 passage from an inlet to an outlet thereof; and

14 changing the position of the condensation shock
15 wave to vary the working fluid discharge from the
16 outlet.

17

18 12. The method according to any of Claims 7 to 11,
19 wherein the transport fluid is steam.

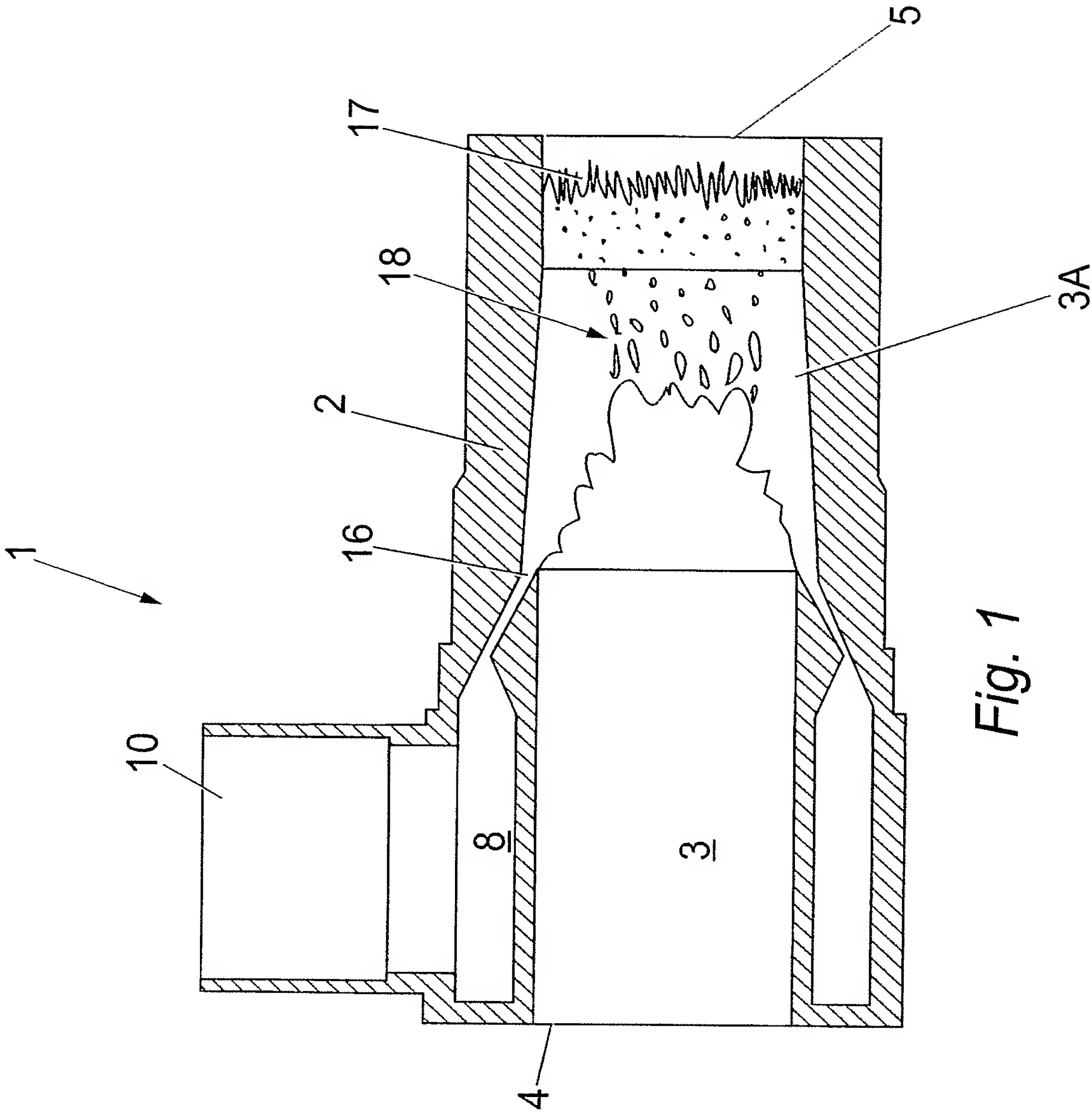
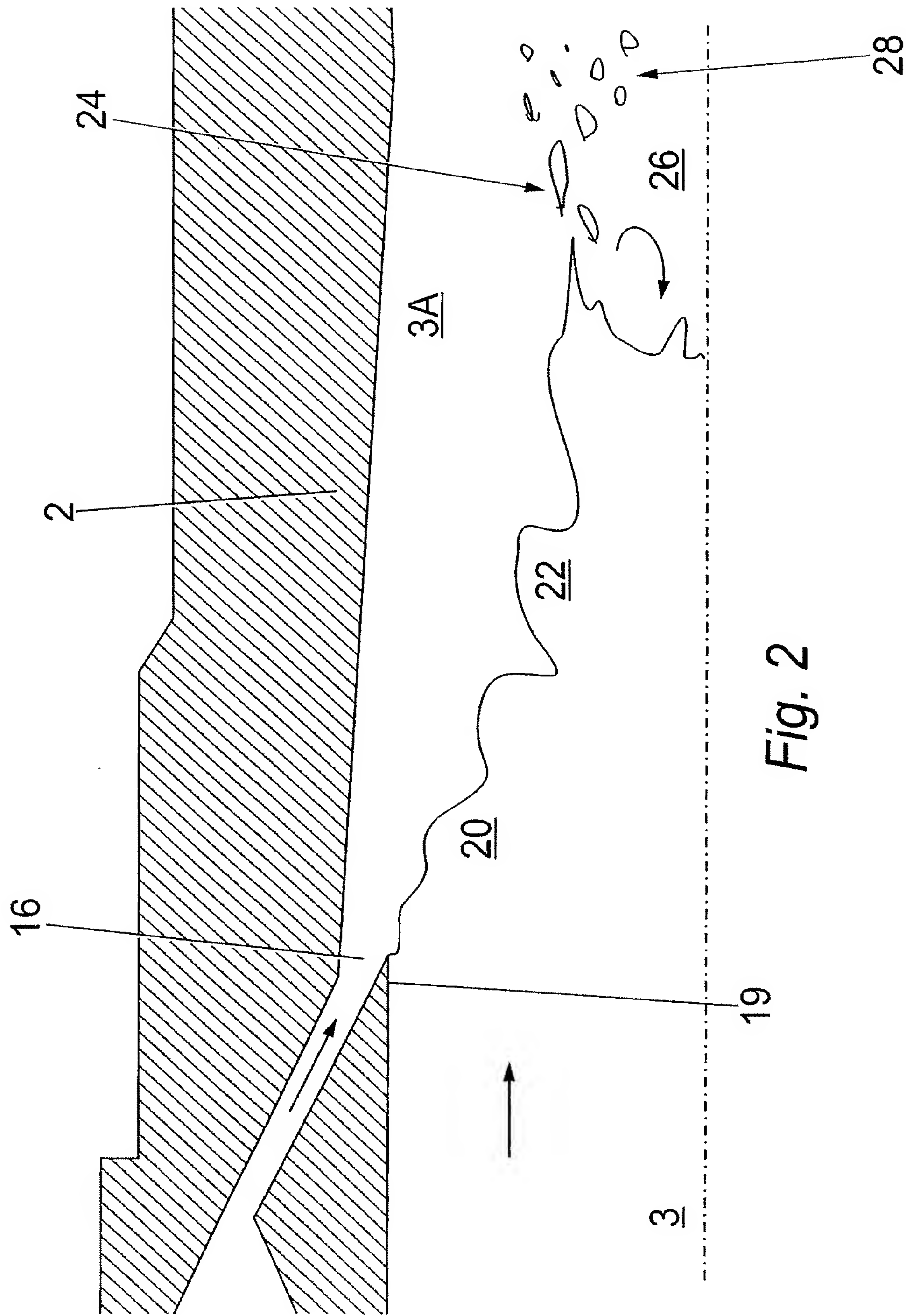
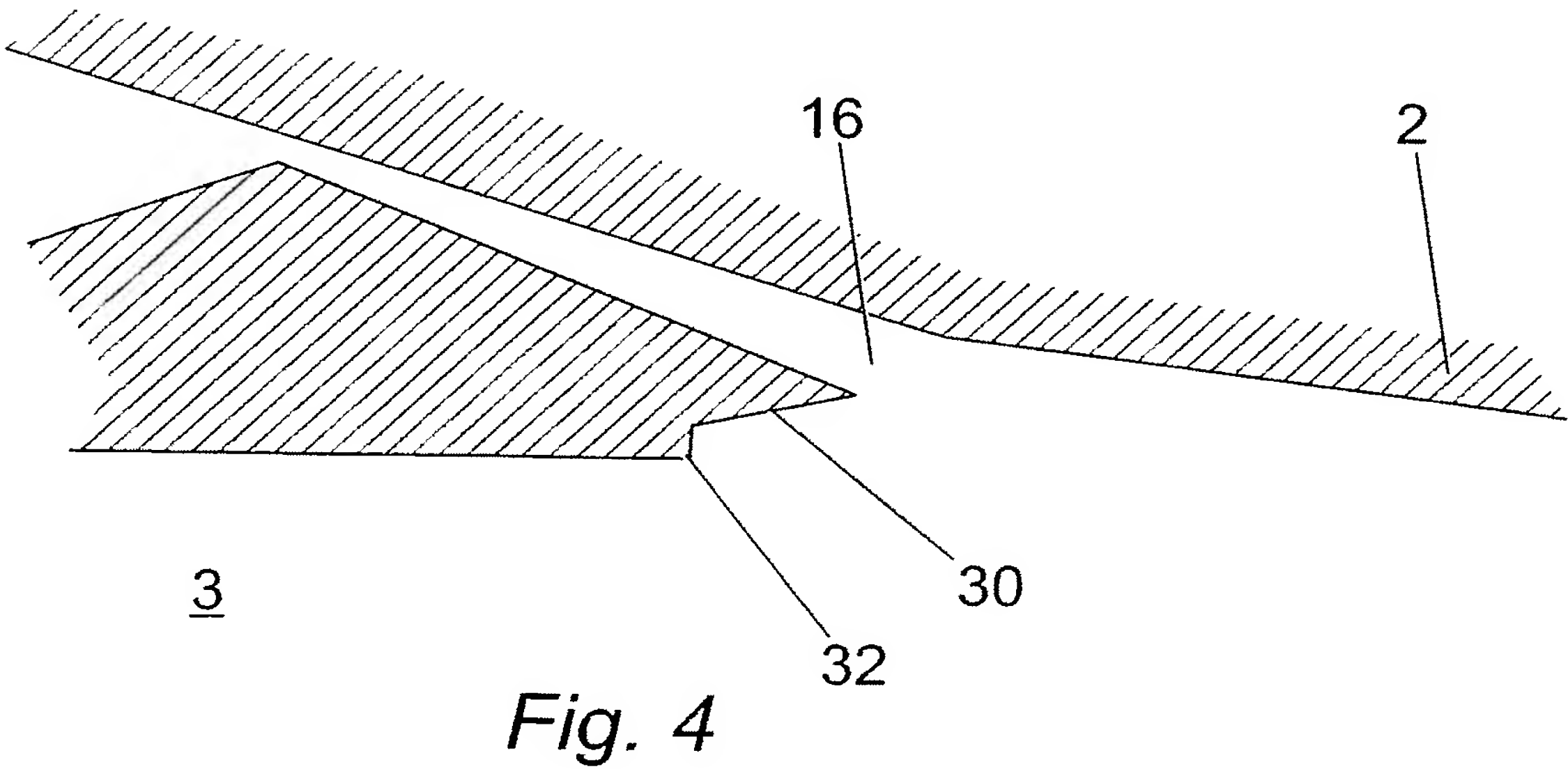
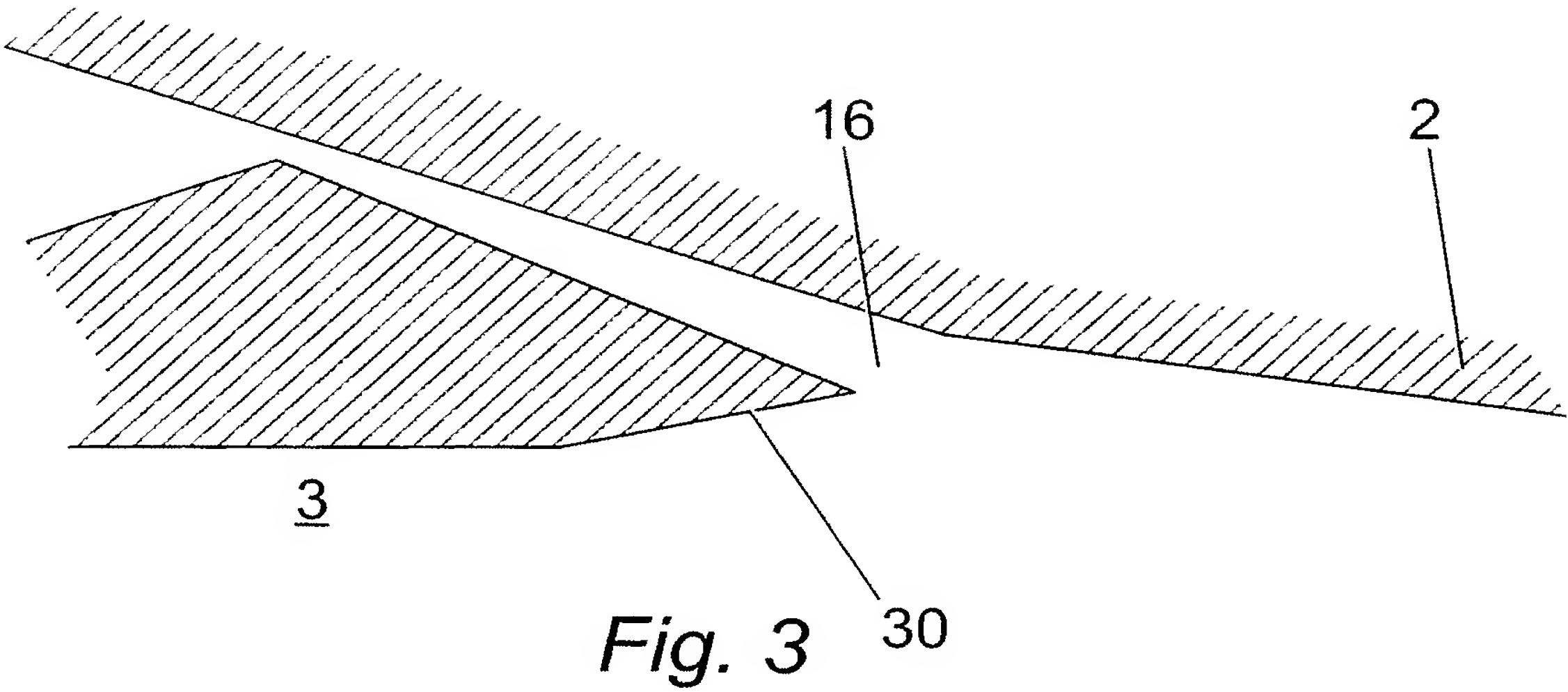


Fig. 1





4 / 9

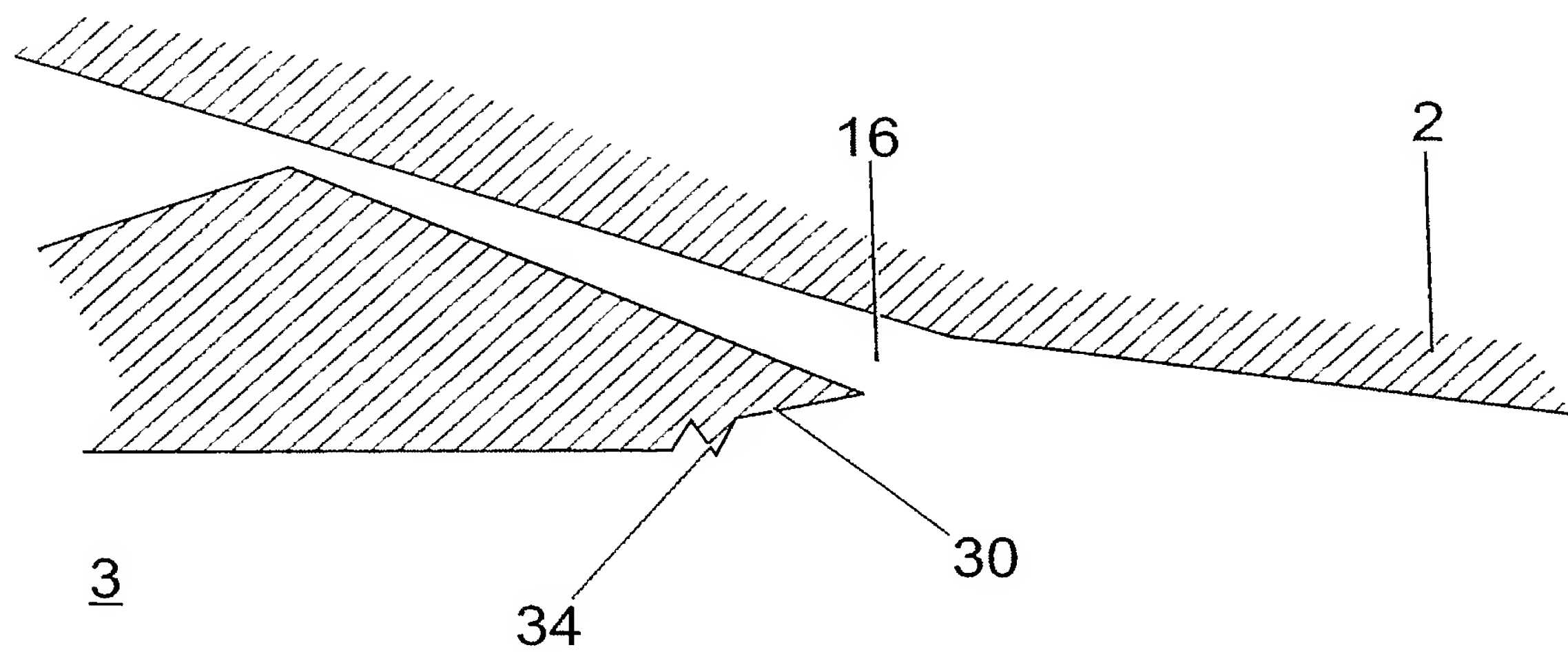


Fig. 5

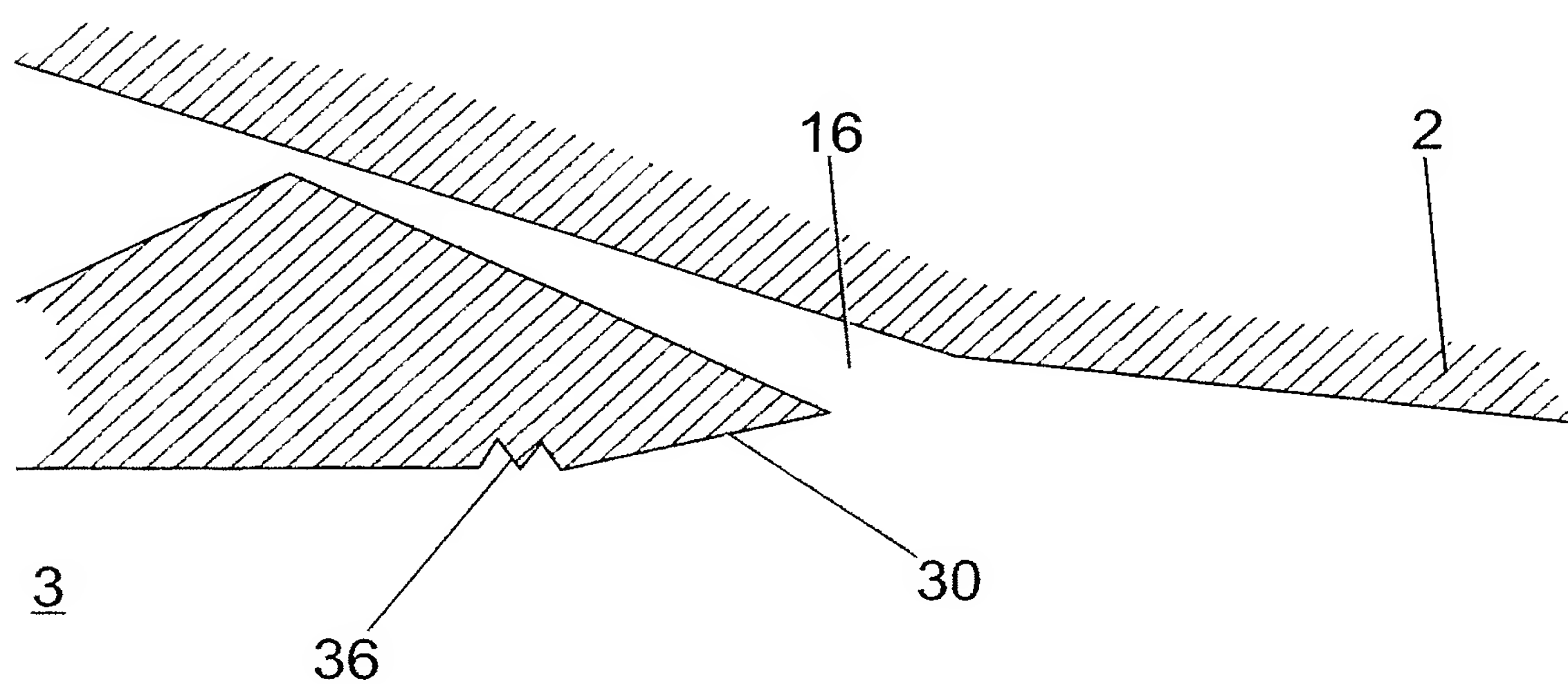


Fig. 6

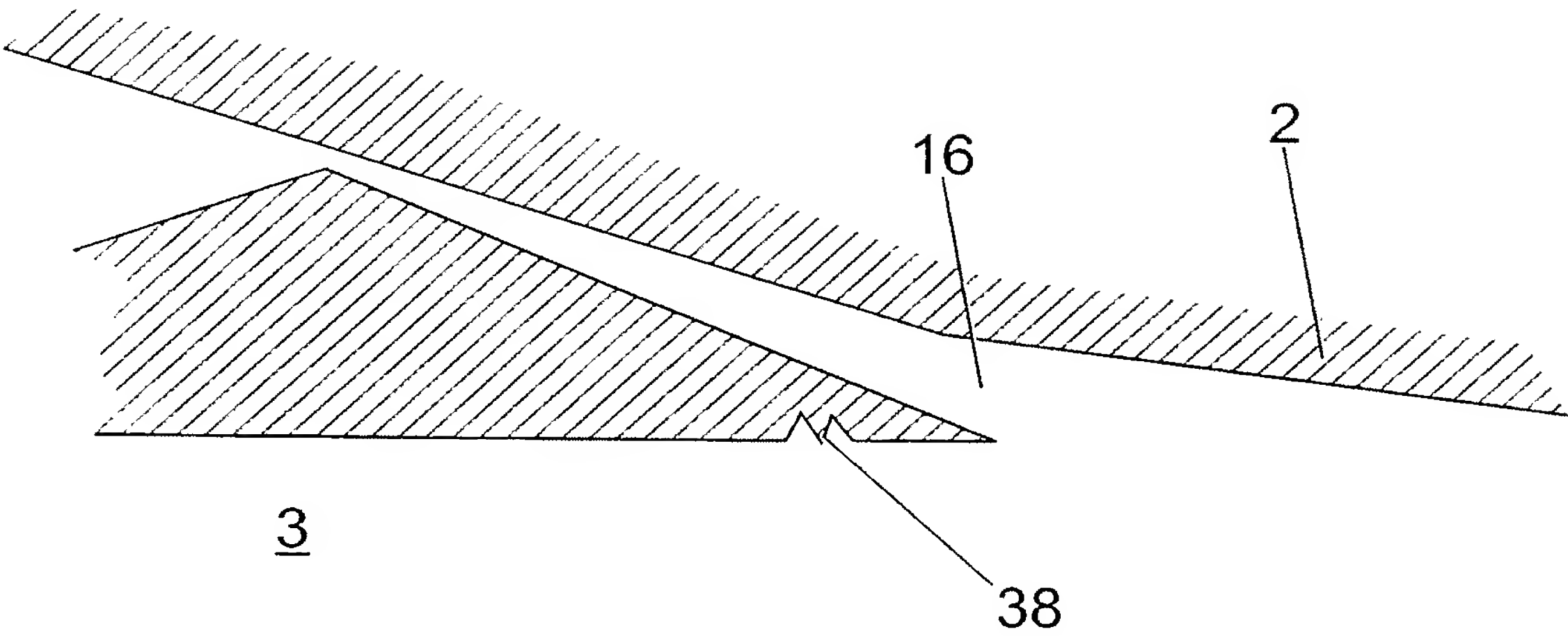


Fig. 7

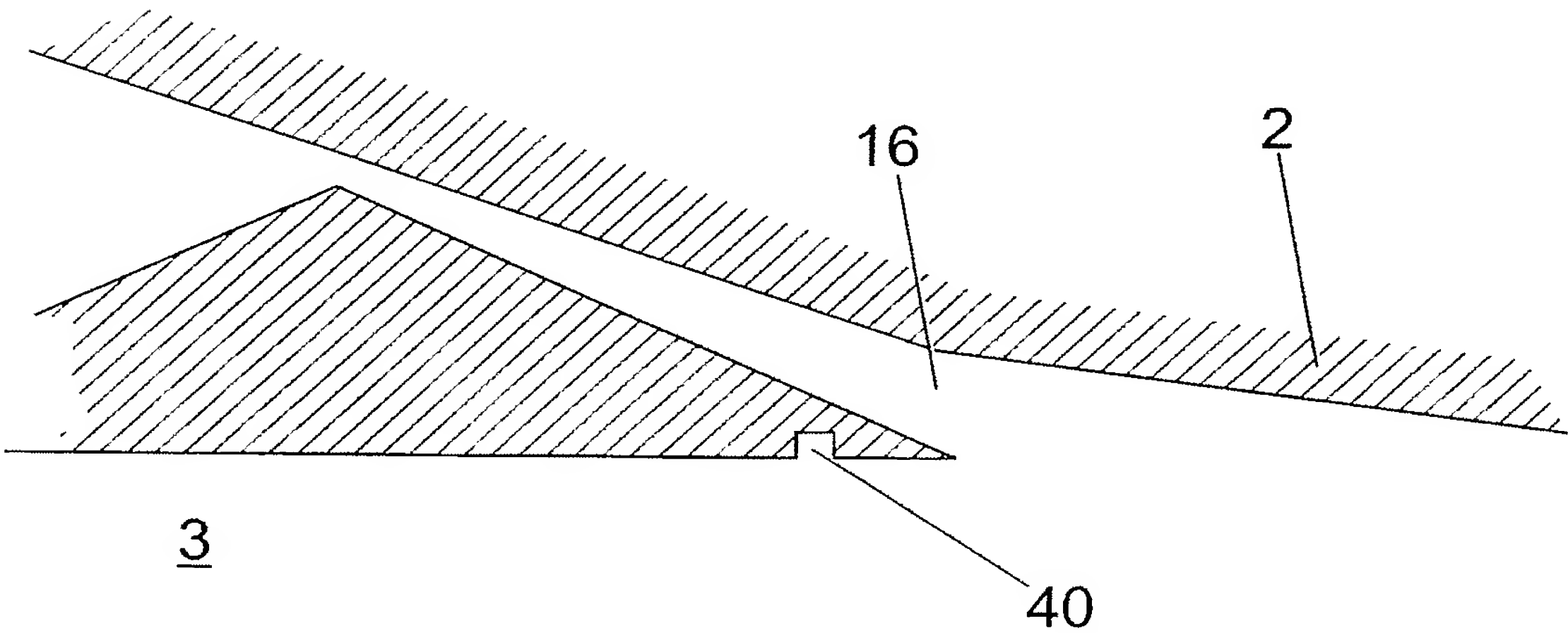


Fig. 8

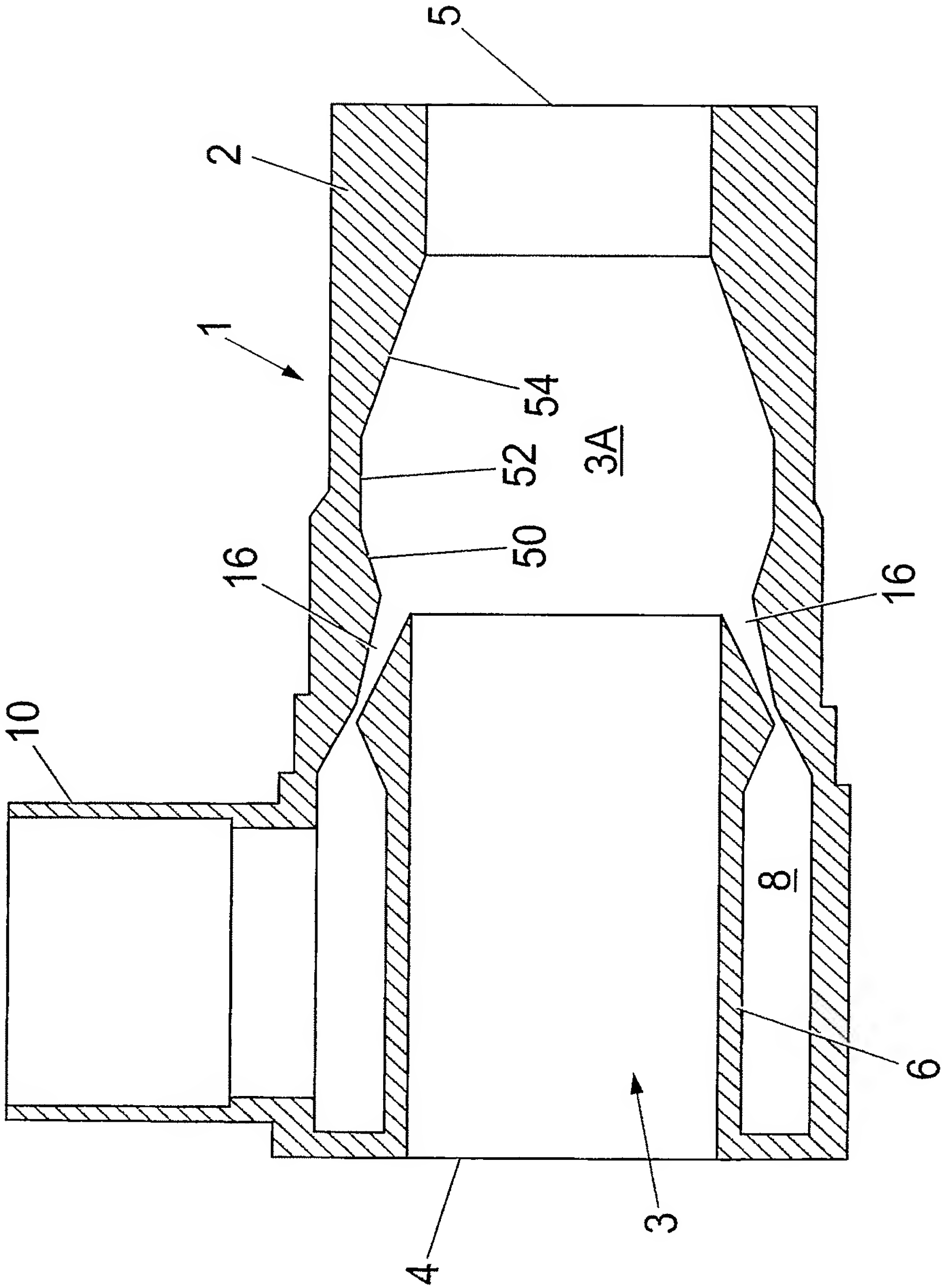


Fig. 9

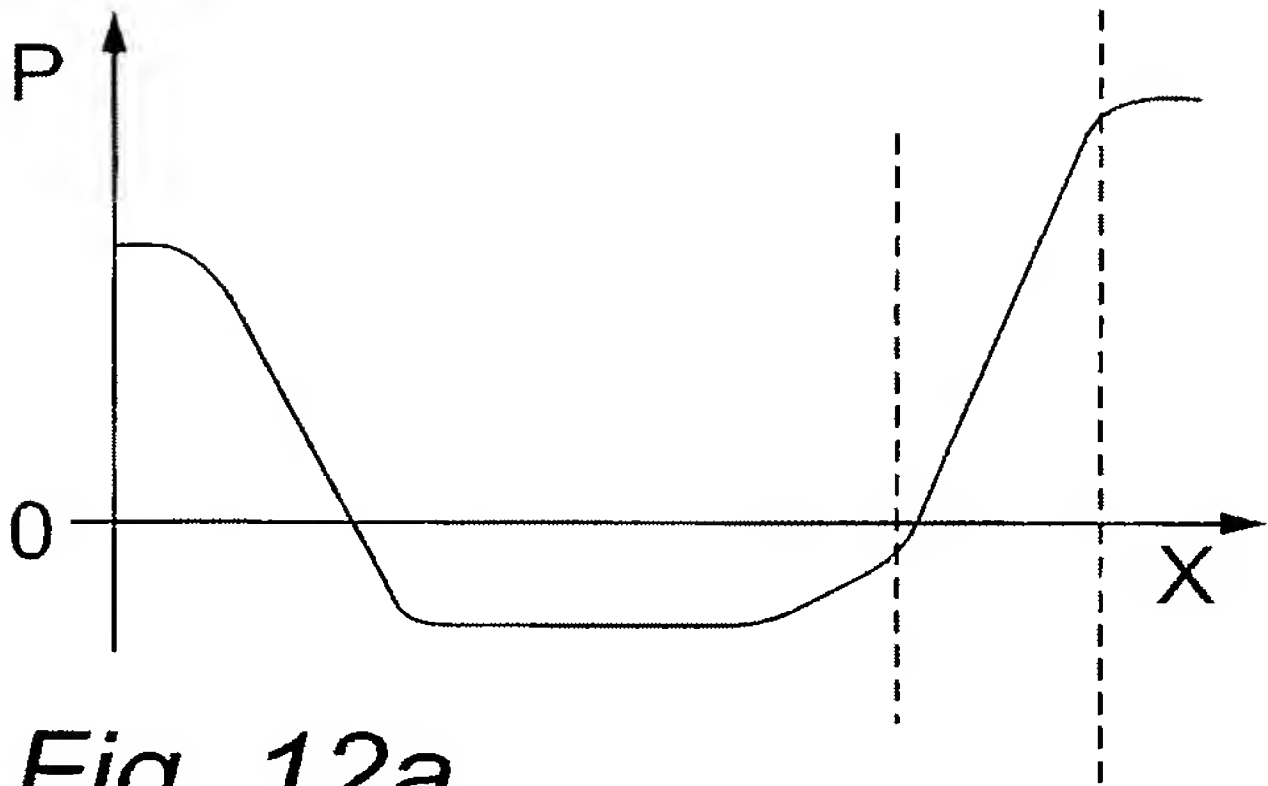


Fig. 12a

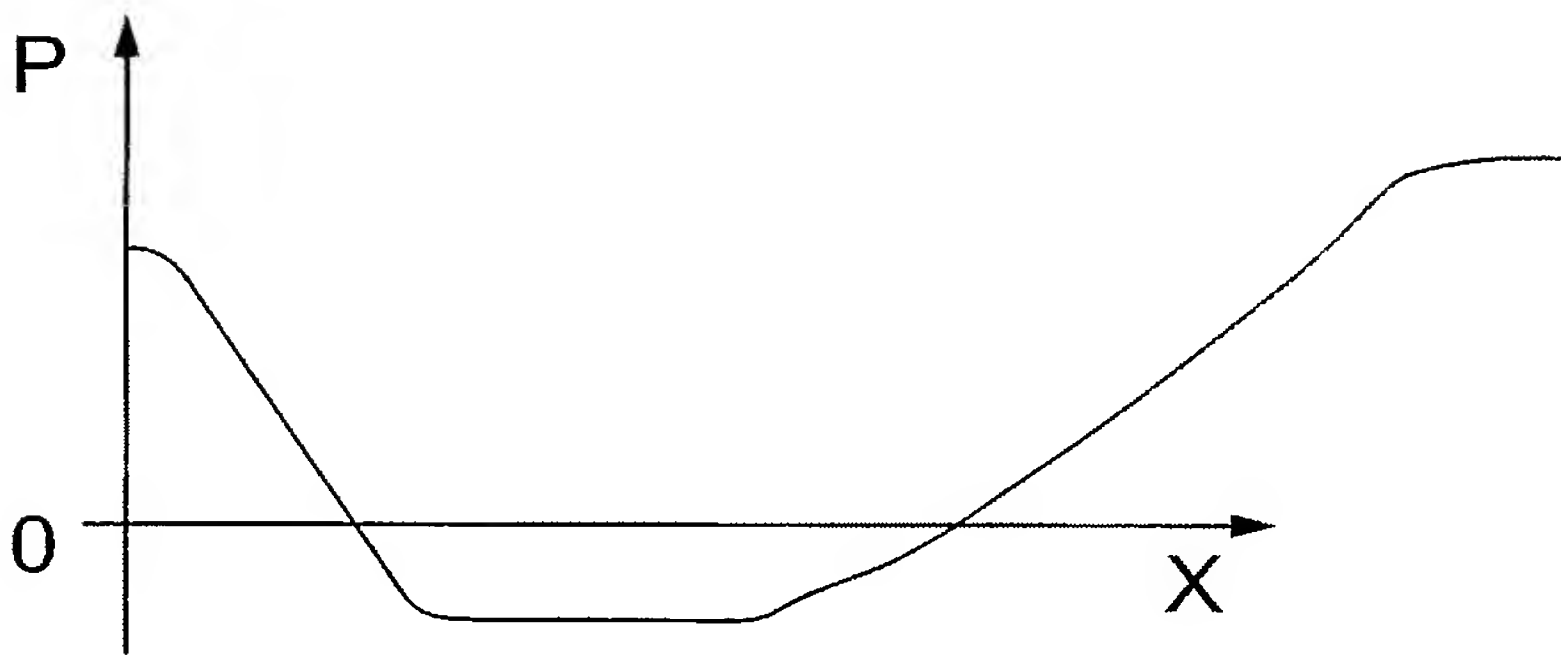


Fig. 12b

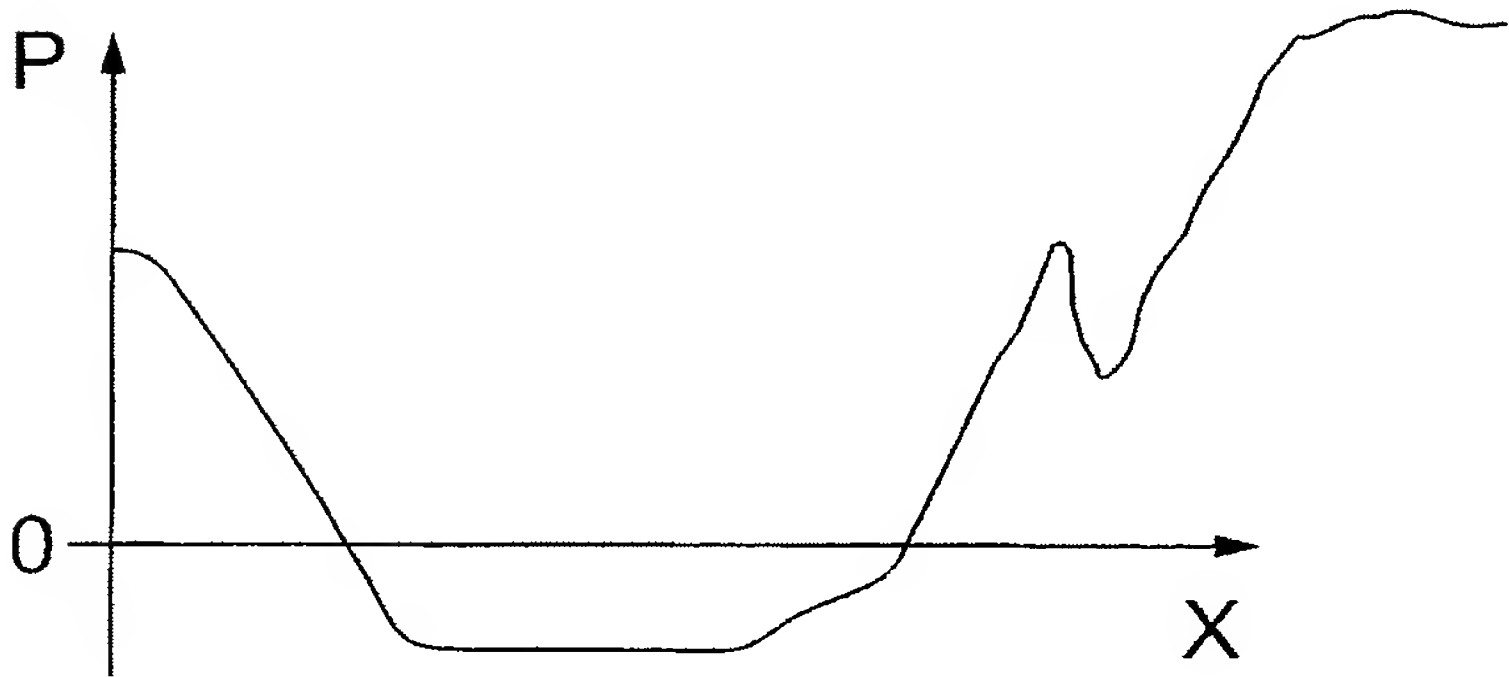
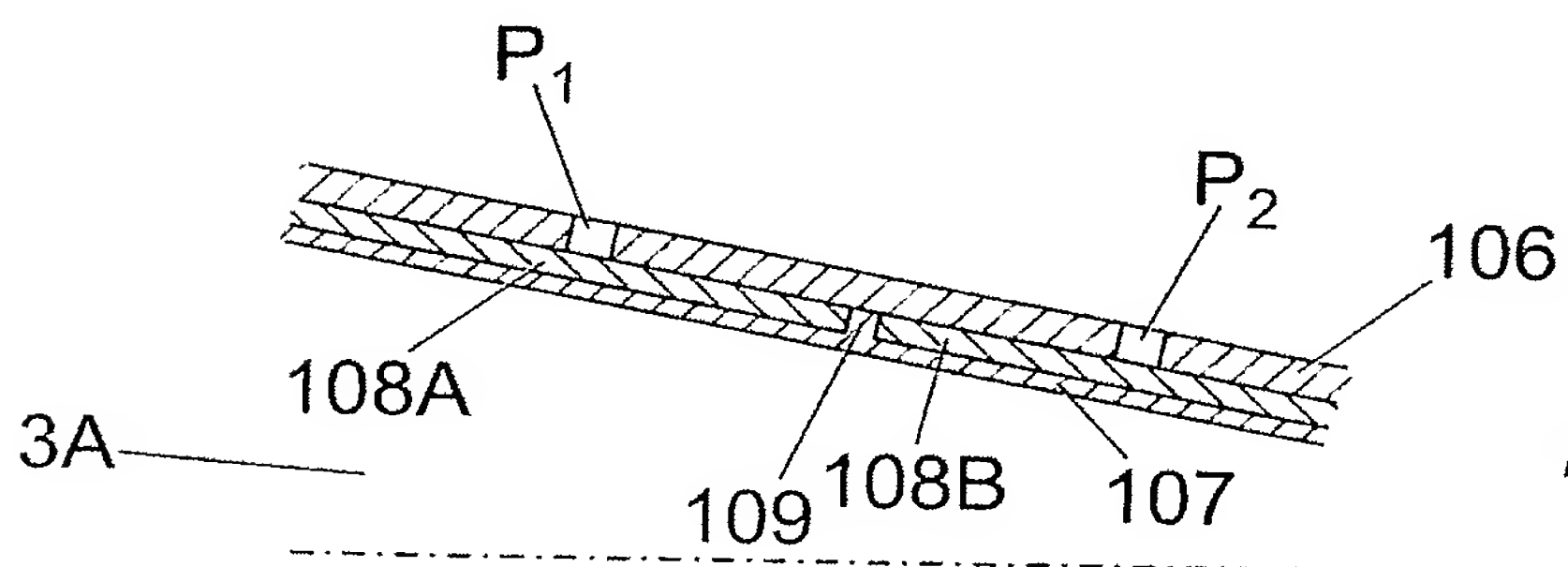
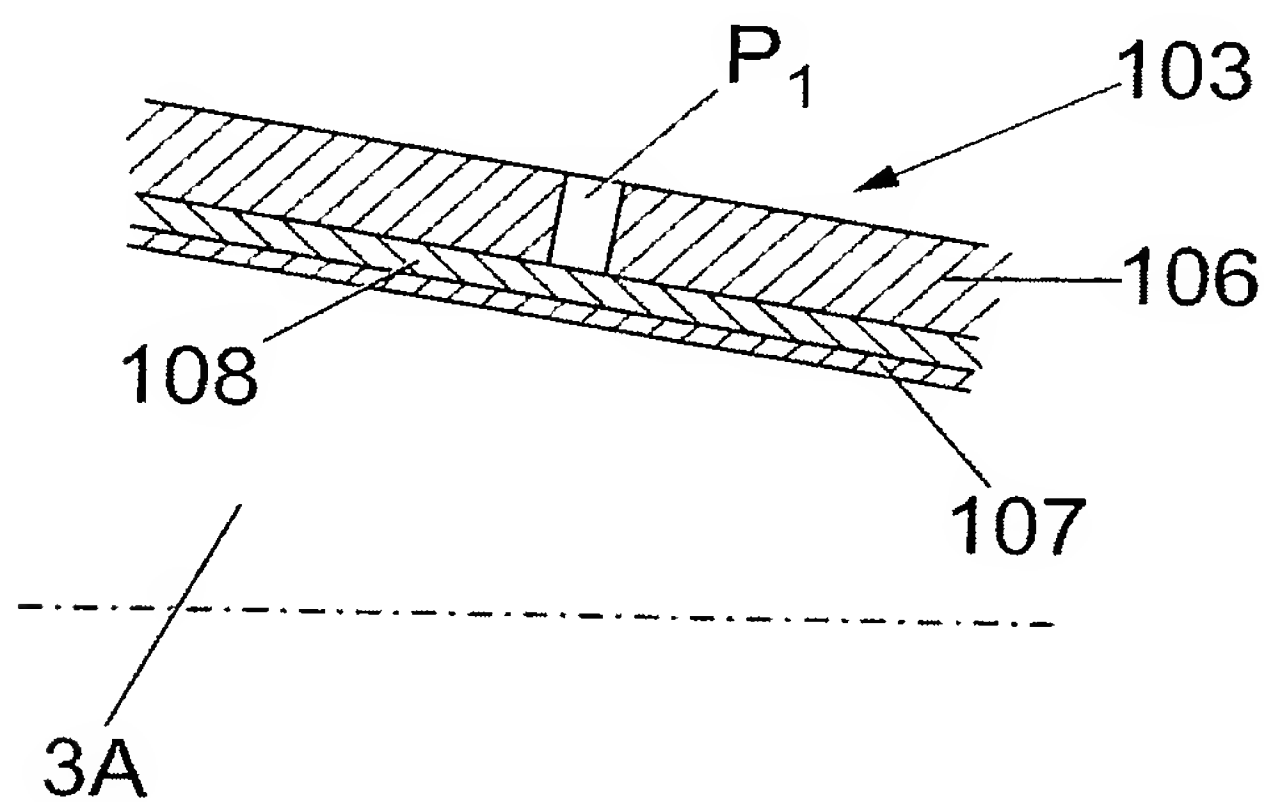
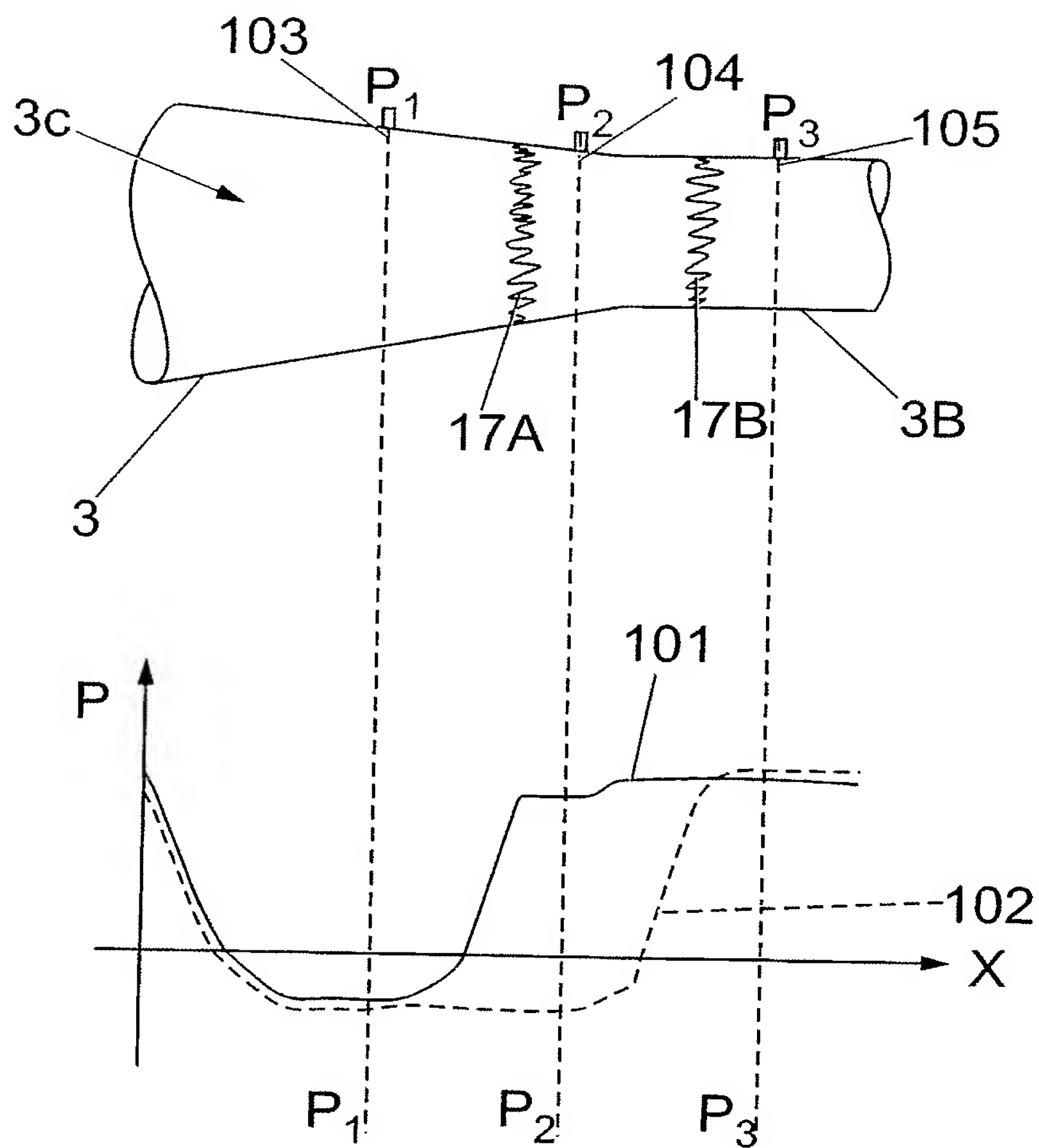


Fig. 12c



INTERNATIONAL SEARCH REPORT

Inte | onal Application No
PCT/GB2005/002999

A. CLASSIFICATION OF SUBJECT MATTER
IPC 7 F04F5/46 F04F5/24

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
IPC 7 F04F

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)
EPO-Internal, PAJ, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	WO 2004/033920 A (PURSUIT DYNAMICS PLC; FENTON, MARCUS, BRIAN, MAYHALL; KITCHEN, PHILIP,) 22 April 2004 (2004-04-22) cited in the application the whole document figures	1-12
X	GB 2 313 410 A (IAN * STEPHENSON; DONOVAN GRAHAM * ELLAM) 26 November 1997 (1997-11-26) abstract	1,5,6
A	page 7, line 18 - page 10, line 31 figures 1-5 ----- -/--	7,11,12

☒ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

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Date of the actual completion of the international search

31 October 2005

Date of mailing of the international search report

10/11/2005

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INTERNATIONAL SEARCH REPORT

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Application No

PCT/GB2005/002999

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

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A	abstract column 3, line 23 - column 6, line 26 figures	7,11
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